



TF-PWA: a general partial wave analysis framework using TensorFlow

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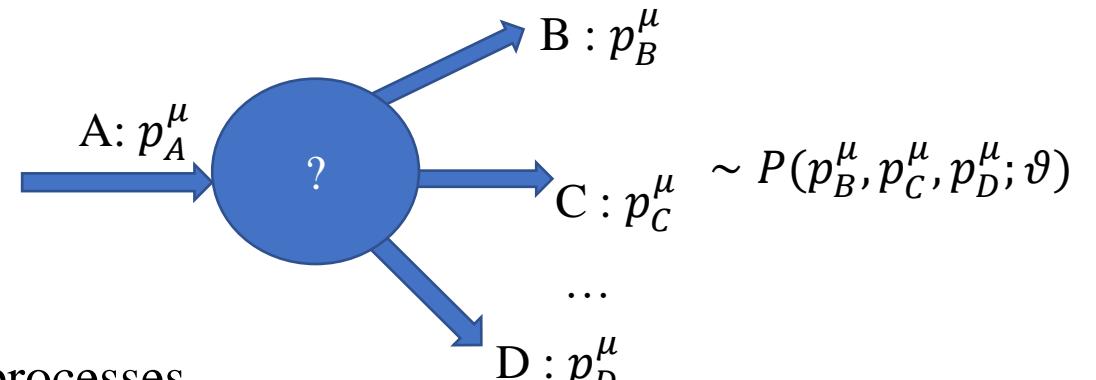
Wednesday April 16, 2025

Outline

- Introduction
- TF-PWA
 - General designs
 - Automatic Differentiation
 - Performances of TF-PWA
- Some analysis using TF-PWA
- Prospect and Summary

Introduction

- Amplitude analysis / Partial wave analysis (PWA) is a powerful method to study multi-body decay processes, e.g.
 - to search for (exotic) resonances and measure their properties
 - to understand CP violation over phase space
- Most of previous fitters are designed for special processes or are time-consuming.
- A general PWA framework using modern acceleration technology (such as GPU, AD, ...) is eagerly needed.

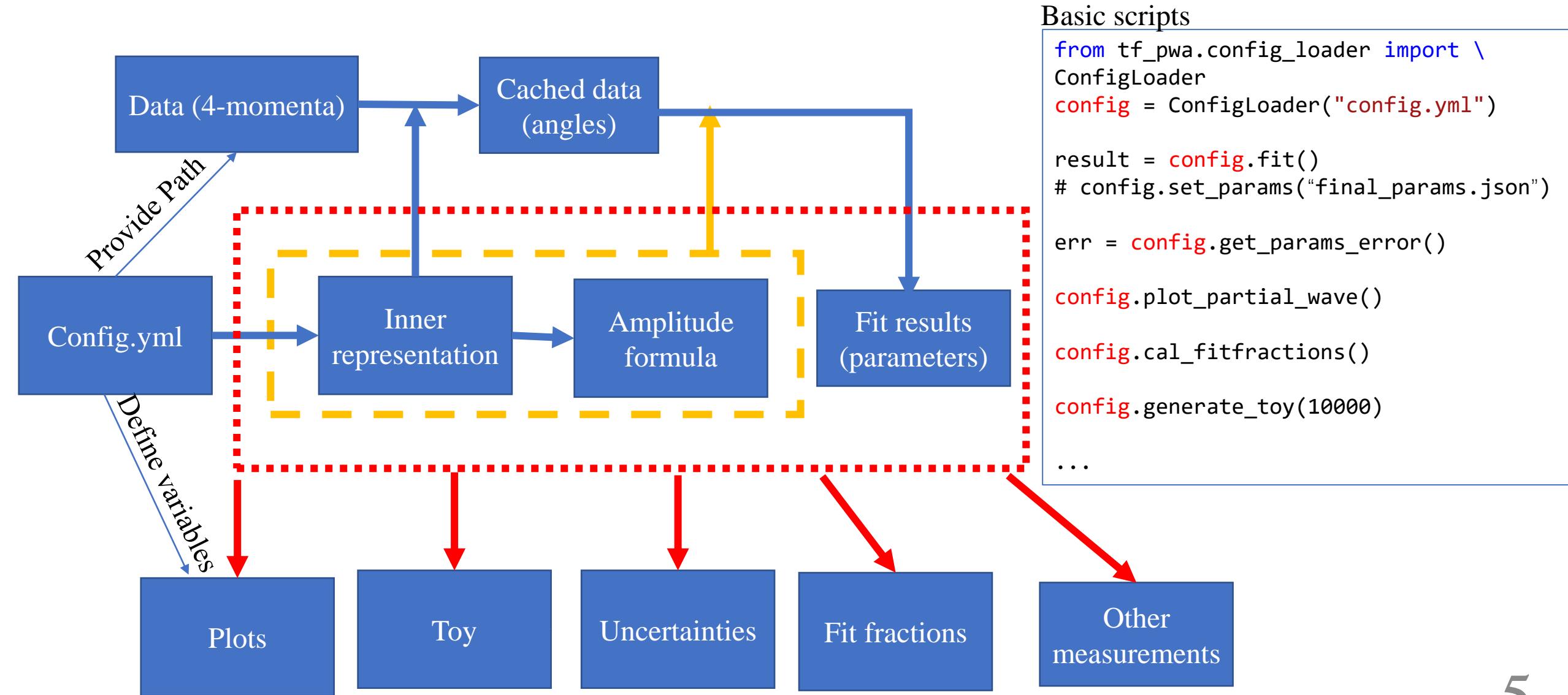


TF-PWA: Partial Wave Analysis with TensorFlow

- Fast
 - GPU based
 - Vectorized calculation
 - Automatic differentiation
 - Quasi-Newton Method: `scipy.optimize`
 - Custom model available
- General
 - Simple configuration file (example provided)
 - Most of the processing is **automatic**
 - All necessary functions implemented
 - Developing more functions
- Easy to use
- Open access and well supported <https://github.com/jiangyi15/tf-pwa>

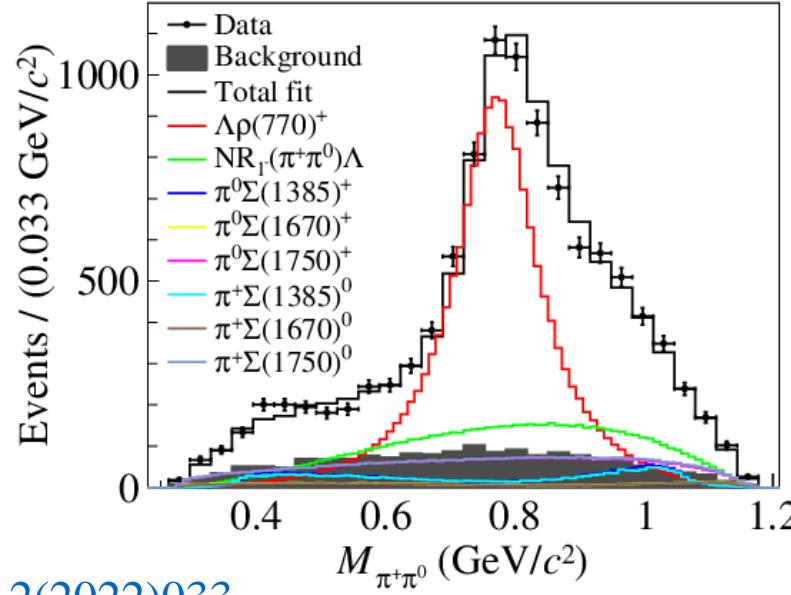
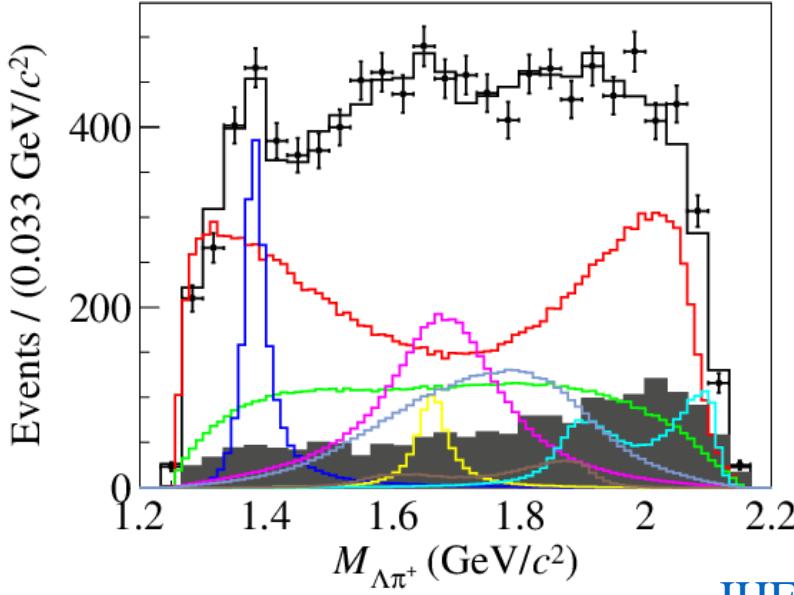


Configuration as global representation



Base Example: $\Lambda_c^+ \rightarrow \Lambda\pi^+\pi^0$

- $\Lambda_c^+ \rightarrow \Lambda(\rightarrow p\pi^-)\pi^+\pi^0$
 - Simultaneous fit
 - 7 energy points
 - Total around 10k events, 854k MC
 - 38 free parameters
 - Dominated by $\Lambda_c^+ \rightarrow \Lambda\rho$: $57.2 \pm 4.2\%$
 - Clear peak for $\Lambda_c^+ \rightarrow \pi\Sigma(1385)$



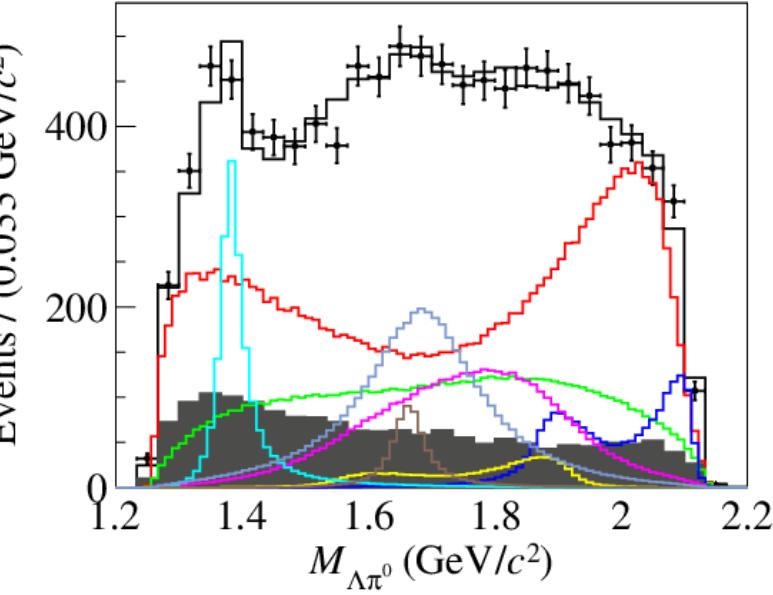
JHEP12(2022)033

The first PWA using TF-PWA
Code: https://github.com/jiangyi15/tf-pwa-example/tree/main/lmd_pipi

Plot thought TF-PWA with simple config.yml
All decay chains will be added automatically

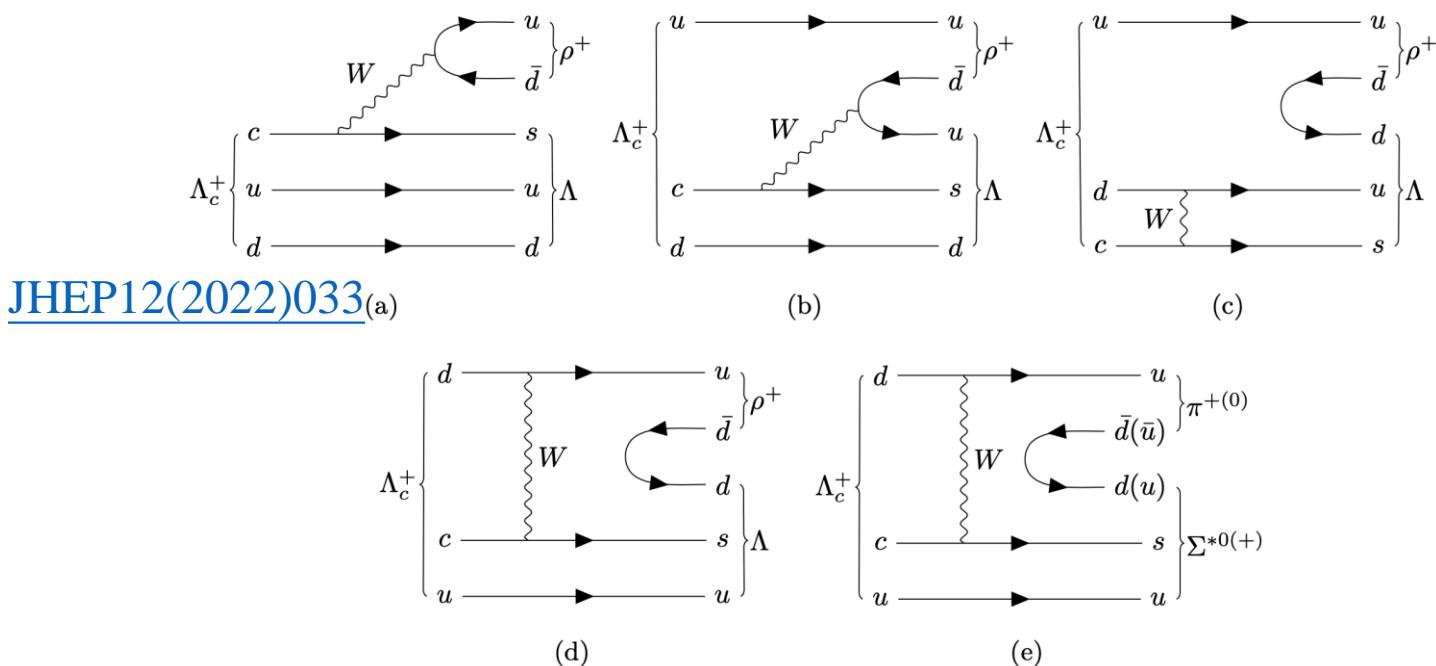
plot:

```
mass:
  Sigma_star0: # name in page 6
  display: "$M_{\Lambda\pi^0\pi^0}$"
  bins: 30
  range: [1.2, 2.2]
  legend: False
```



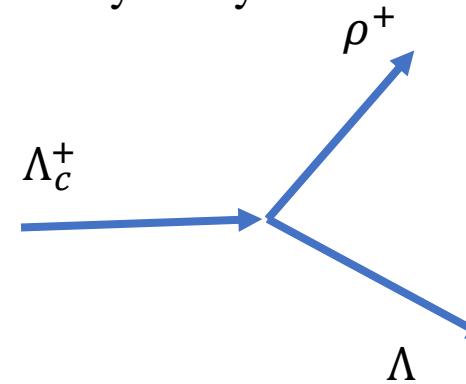
Configuration

- What is needed?
 - Particles (Resonances, line) and their properties
 - Decays (interaction, vertex) and their properties
- Store in dict or list, save as YAML file.
- Possible process in this Λ_c^+ decay $\Lambda_c^+ \rightarrow \Lambda \pi^+ \pi^0$



YAML: <https://yaml.org>

2-body decay



Serialize as

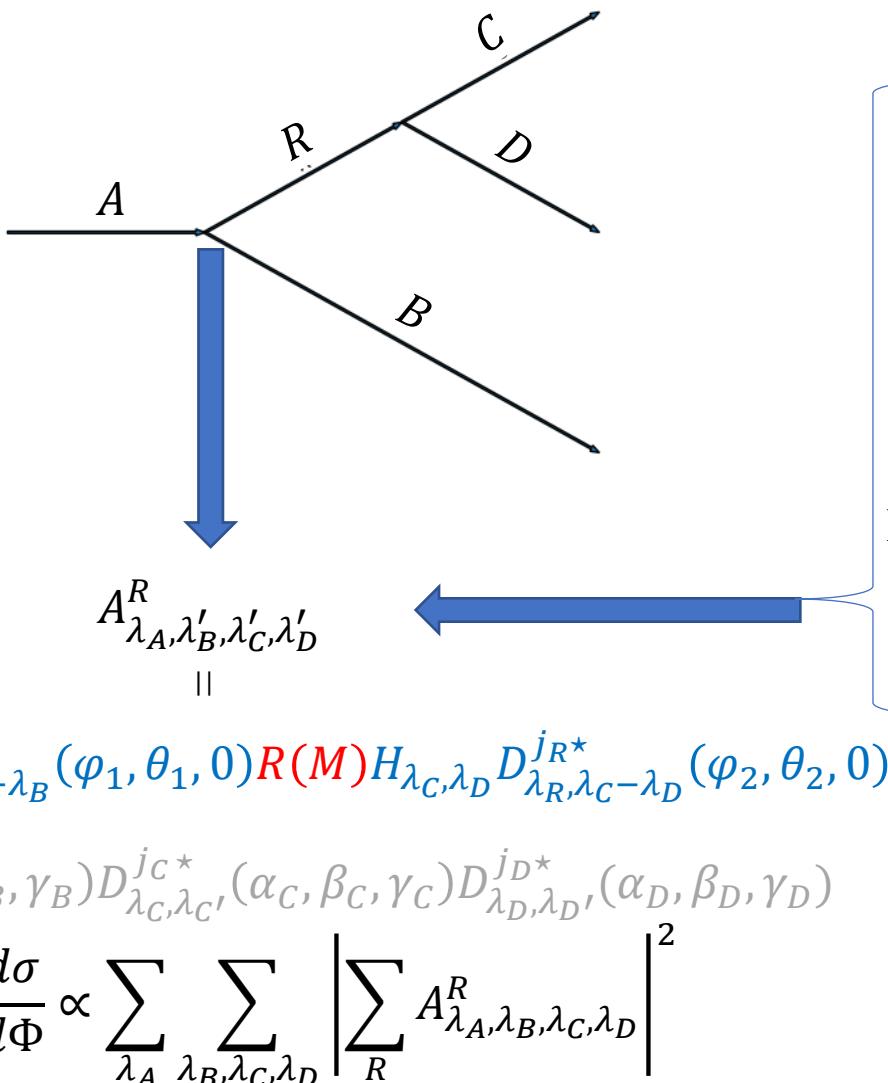
```
Lambda_c: [
    [Lambda, rho],
    [Sigma_starp, pi0 ],
    [Sigma_star0, pip ],
]
```

```
rho:
  J: 1
  P: -1
  mass: 0.77511
  width: 0.1491
  model: GS_rho
  ...
```

Config.yml In TF-PWA

Helicity formalism

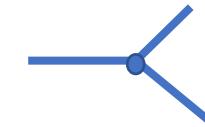
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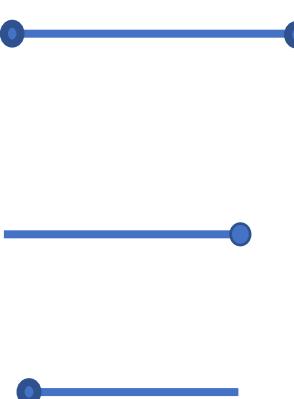
Automatically calculated from decay structure

Feynman rules

Decay



Particle



User defined

$$A^{0 \rightarrow 1+2} = H_{\lambda_1, \lambda_2} D_{\lambda_0, \lambda_1 - \lambda_2}^{j_0 \star}(\varphi, \theta, 0)$$

Wigner-D matrix

$$R(M) = \frac{1}{m_0^2 - M^2 - im_0\Gamma}, \dots$$

$$1 \text{ or } \rho = 1 + \vec{p} \cdot \vec{\sigma}$$

$$D_{\lambda_1, \lambda_1'}^{j_1 \star}(\alpha, \beta, \gamma)$$

alignment

probability: $|\mathcal{A}|^2$

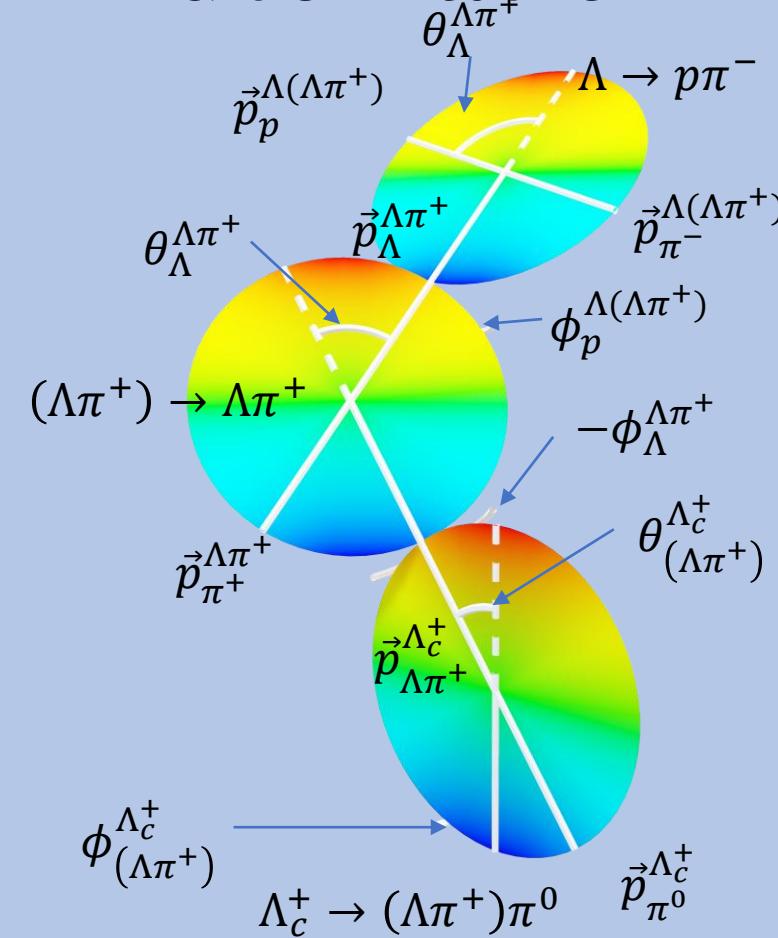
Decay Group: $\mathcal{A} = \tilde{A}_1 + \tilde{A}_2 + \dots$

Decay Chain: $\tilde{A} = A_1 R A_2 \dots$

Decay: Wigner D-matrix, $A = HD^{*J}(\phi, \theta, 0)$

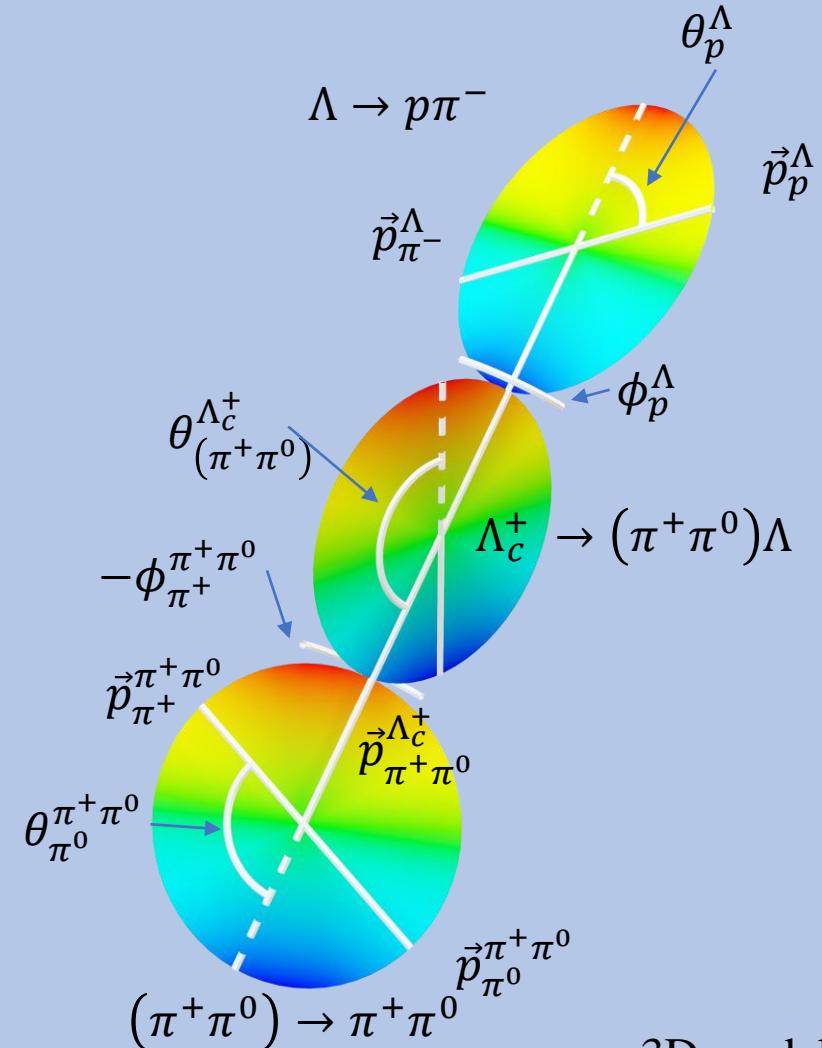
Particle: Breit-Wigner: $R(m)$, user defined

Automatic Angle Plot

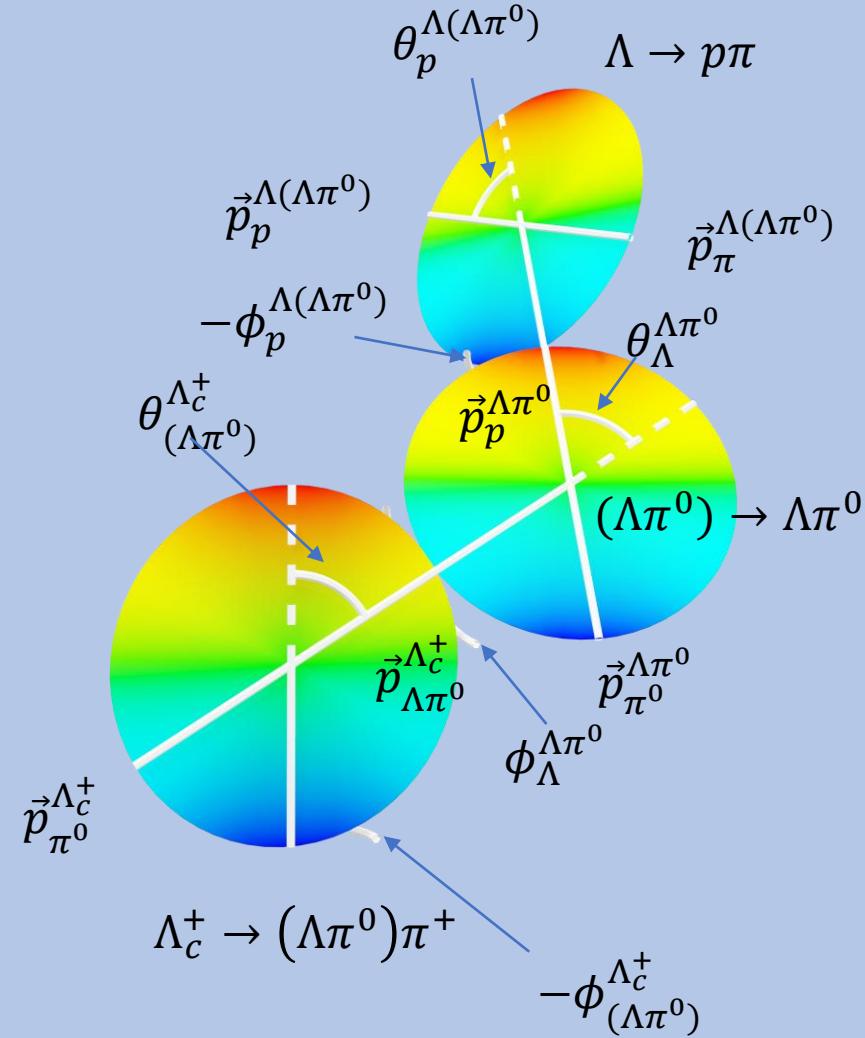


Auto calculated by TF-PWA,
Only required the 4-momenta

TF-PWA also provide reverse process:
Mass + helicity angle \rightarrow 4-momenta



\vec{p}_B^A means momentum of B in the rest frame of A
 ϕ means the rotation is anticlockwise, while $-\phi$ for clockwise
The sign is dependent on data



3D model generated by a script using TF-PWA.

Alignment

- Problem found in pentaquark study (θ_p)
- Helicity formula
 - Required addition alignment of different decay chain
- General formula of alignment
 - The rotation part: $R = \Lambda(Lp)^{-1}L\Lambda(p)$, for a general Lorentz transformation (L)
 - $\Lambda(p)$ is a pure boost from a reference momentum to momentum p
 - R keeps the same reference momentum: $Rp_0 = p_0$,
 - $p_0 = (m_0, 0, 0, 0)$, $m_0 \neq 0$
 - $p_0 = (1, 0, 0, 1)$ for massless particle
 - $R = \Lambda(L_2 p)^{-1} L_2 \Lambda(L_1 p) \Lambda(L_1 p)^{-1} L_1 \Lambda(p) = \Lambda(L_2 p)^{-1} L_2 L_1 \Lambda(p)$
 - Irreducible tensor formula,
 - helicity formula
 - In helicity formula
 - p, Lp are all in z-axis (as the definition of helicity), so $\Lambda(Lp)^{-1}, \Lambda(p)$ is B_z
 - B_z does not affect the angle calculation.
 - TF-PWA provides additional option for alignment:
 - [align_ref: center_mass](#): align to spin projection in z-axis instead of helicity.

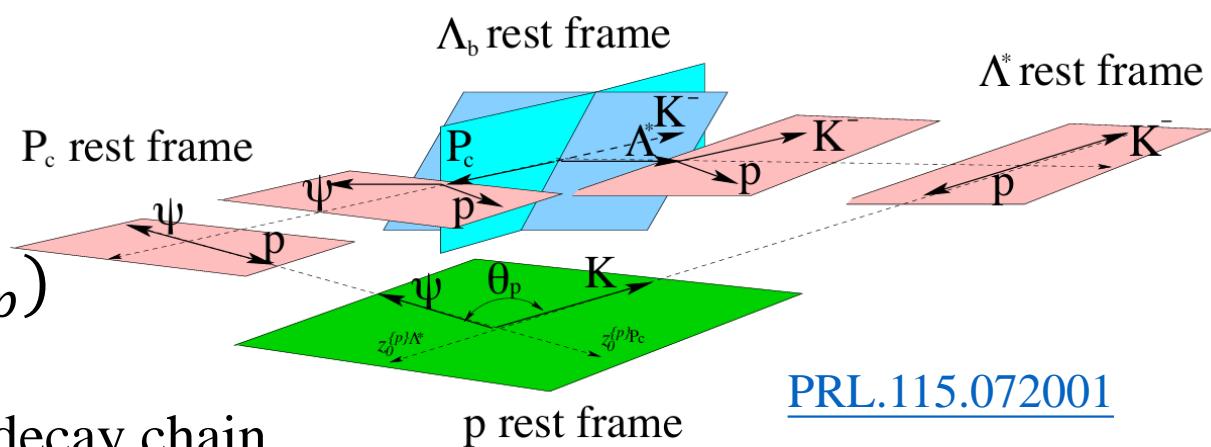


Figure 18: Definition of the θ_p angle.

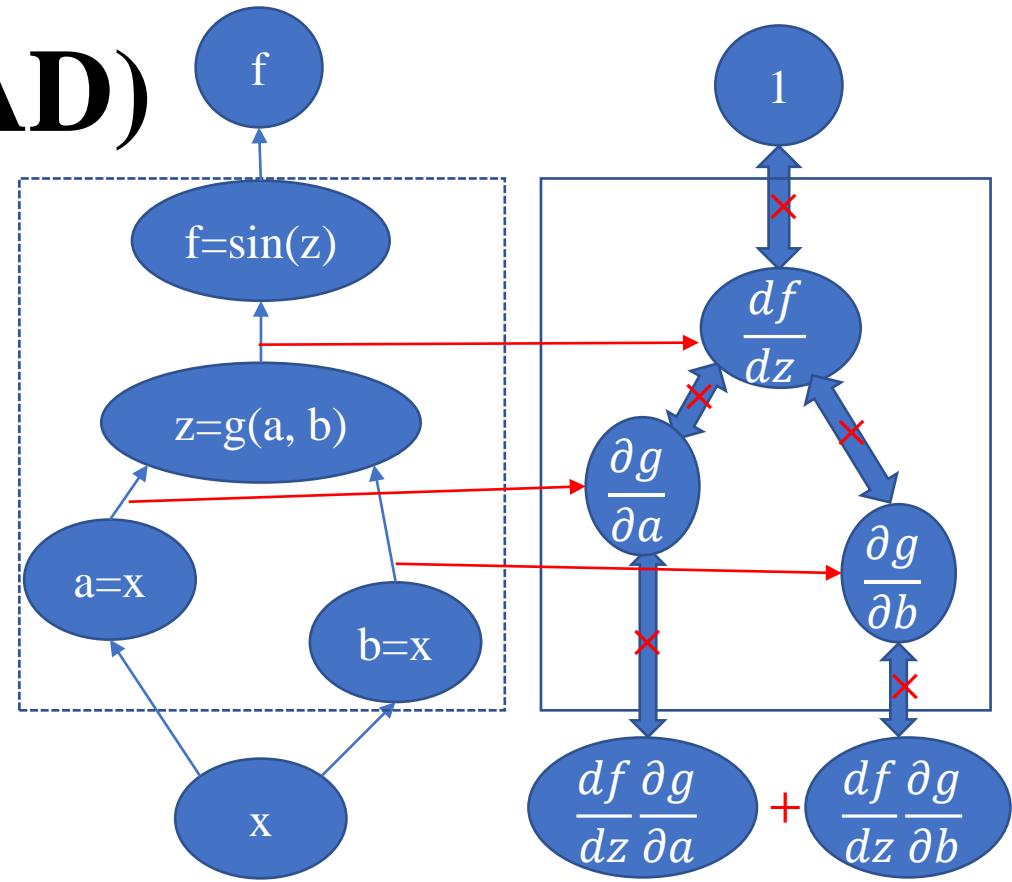
Automatic Differentiation(AD)

- Widely used in Optimization problem
 - Calculate gradient automatically
 - No need for exact formula.
 - Recorded the computation graphs.
 - Operator: function used (\sin , g)
 - Intermediate value: ($z = 1^1$)
 - Mostly matrix form (Jacobian).
 - Just combine the operator (Chain Rules)

Chain Rules

- \times : $\frac{\partial f(g(x))}{\partial x_i} = \frac{df}{dg} \times \frac{\partial g}{\partial x_i}$
- $+$: $\frac{\partial f(h(x), g(x))}{\partial x_i} = \frac{\partial f}{\partial h} \frac{\partial h}{\partial x_i} + \frac{\partial f}{\partial g} \frac{\partial g}{\partial x_i}$

The same rule-based method as our amplitude calculation.



$$f = \sin(x^x) = \sin(z), z = x^x$$

$$g(a, b) = a^b$$

Automatic Differentiation (numerically):

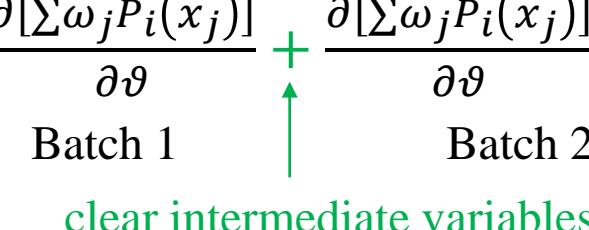
$$\frac{df}{dx}(1) = \frac{df}{dz}(1^1) \left[\frac{\partial g}{\partial a}(1, 1) + \frac{\partial g}{\partial b}(1, 1) \right] = 0.5403$$

→ backward

AD in amplitude fit

- Minimize of $-\ln L(\vartheta)$
 - $-\frac{\partial \ln L}{\partial \vartheta}$ is the steepest descent direction, used by most of optimizer
 - Error matrix $V_{ij} = \left[-\frac{\partial^2 \ln L}{\partial \vartheta_i \partial \vartheta_j} \right]^{-1}$ can also be estimated though AD
 - AD advantage:
 - Automatic.
 - Fast estimation: Time cost for eval $-\ln L(\vartheta)$ and $-\frac{\partial \ln L}{\partial \vec{\vartheta}}$ are on the same level.
 - Accurate gradient: more stable results.
 - AD disadvantage:
 - Require well defined gradients (**continuous**).
 - Avoid step function, delta function.
 - Only support function with **predefined gradients**.
 - Use TensorFlow only, but also have an interface to define functions.
 - Large (GPU) memory cost for **recording intermediate values**.
 - Split data into small batches (discuss later).

AD in Large size of data

- Basic Log-Likelihood function
 - $\ln L(\vartheta) = \sum \ln \left[(1 - f_2) \frac{P_1(x; \vartheta)}{\int P_1(x; \vartheta) dx} + f_2 \frac{P_2(x; \vartheta)}{\int P_2(x; \vartheta) dx} \right]$
 - $I_i = \int P_i(x) dx \approx \sum \omega_j P_i(x_j)$
 - Required recording all $P_i(x_j)$ and intermediate values before gradients evaluations.
- Split large data into small batches (only record value in a small batch)
 - $\ln L(\vartheta) \Rightarrow \ln L(\vartheta; I_i)$
 - $\frac{\partial \ln L(\vartheta)}{\partial \vartheta} \Rightarrow \frac{\partial \ln L(\vartheta; I_i)}{\partial \vartheta} + \sum_i \frac{\partial \ln L(\vartheta; I_i)}{\partial I_i} \frac{\partial I_i}{\partial \vartheta}$
 - $\frac{\partial I_i}{\partial \vartheta} = \frac{\partial [\sum \omega_j P_i(x_j)]}{\partial \vartheta} + \frac{\partial [\sum \omega_j P_i(x_j)]}{\partial \vartheta} + \dots$ 
- Expand the power of AD to multi GPU, even multi cluster

AD for error propagation

- Error propagation
 - $\sigma_y^2 = \frac{\partial y}{\partial x} \sigma_x^2 \frac{\partial y}{\partial x}$, $\frac{\partial y}{\partial x}$ can be calculated by AD
 - Simple interface (see right)
 - Example: uncertainties of fit fractions in TF-PWA
- Advance usage
 - Define function with gradient
 - AD + some part of numerical function
 - $\frac{\partial f}{\partial x} = \frac{\partial f}{\partial g} \frac{\partial g}{\partial h} \frac{\partial h}{\partial x}$, numerical: $\frac{\partial g}{\partial x} = \frac{g(x+\Delta x) - g(x-\Delta x)}{2\Delta x}$
 - Example: Obtain pole mass in TF-PWA (a iteration process)
 - Systematic uncertainties of fixed parameters (fixed mass and width)
 - $-\ln L = -\ln L(\vartheta, z)$, ϑ : fit parameters, z : fixed parameters
 - Minimum condition as **implicit function**
 - $-\frac{\partial \ln L}{\partial \vartheta} = 0 \Rightarrow \frac{\partial \vartheta_i}{\partial z} = - \left[\frac{\partial^2 \ln L}{\partial \vartheta_i \partial \vartheta_j} \right]^{-1} \frac{\partial^2 \ln L}{\partial \vartheta_j \partial z}$

```
with config.params_trans() as pt:
    # g1 is fixed to 1
    g2_r = pt["Lmdc->piz.Sigma(1385)p_g_ls_1r"]
    g2_phi = pt["Lmdc->piz.Sigma(1385)p_g_ls_1i"]
    alpha = 2*g2_r*tf.cos(g2_phi) / (1+g2_r*g2_r)
    print(alpha, pt.get_error(alpha))
```

$$\alpha_{\Sigma(1385)\pi} = \frac{|H_{0,\frac{1}{2}}^{\Sigma(1385)}|^2 - |H_{0,-\frac{1}{2}}^{\Sigma(1385)}|^2}{|H_{0,\frac{1}{2}}^{\Sigma(1385)}|^2 + |H_{0,-\frac{1}{2}}^{\Sigma(1385)}|^2}$$

$$= \frac{2\Re \left(g_{1,\frac{3}{2}}^{\Sigma(1385)} \cdot \bar{g}_{2,\frac{3}{2}}^{\Sigma(1385)} \right)}{|g_{1,\frac{3}{2}}^{\Sigma(1385)}|^2 + |g_{2,\frac{3}{2}}^{\Sigma(1385)}|^2}$$

```
decay = config.get_decay()
p = decay.get_particle("Sigma(1385)p")
with config.params_trans() as pt:
    pole = p.solve_pole()
    re = tf.math.real(pole)
    im = tf.math.imag(pole)
    print((re, im), pt.get_error((re, im)))
```

Different preprocess

data:

...
preprocessor: cached_shape
amp_model: cached_shape

- Implement different ways for amplitude
 - Option in config.yml: preprocessor and amp_model
 - Balance performance and memory usage.
- Performance of data:MC = 1:10
 - Linear performance of data size
 - Boundary of memory size

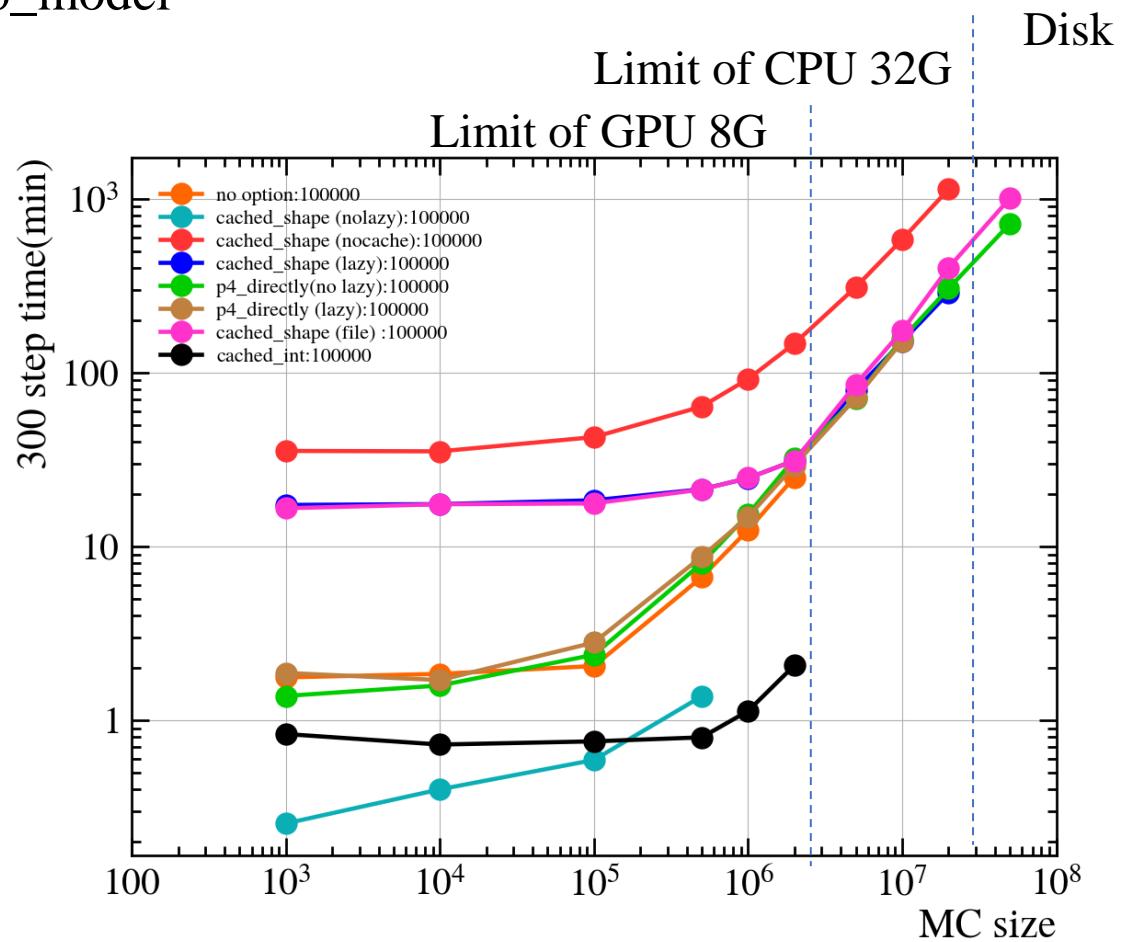


options	pre-process	amplitude
default	$p^\mu \rightarrow m, angle$	$c_i f_i(m) T_i(angle)$
cached_amp	$p^\mu \rightarrow m, angle, T_i$	$c_i f_i(m) T_i$
cached_shape	$p^\mu \rightarrow m, angle, T_i$ $f_j T_j$	$c_i f_i(m) T_i$ $c_j f_j T_j$
p4-directly	p^μ	$p^\mu \rightarrow m, angle$ $c_i f_i(m) T_i(angle)$

Table 1: Calculation in the two parts

data	memory requirement for one event
p^μ	4 N(particles)
m	N(particles)
$angle$	6 N(chain) N(decay in one chain) 3 N(chain) N(final particles)
$f_i T_i, T_i$	N(partial waves)N(helicity combination)

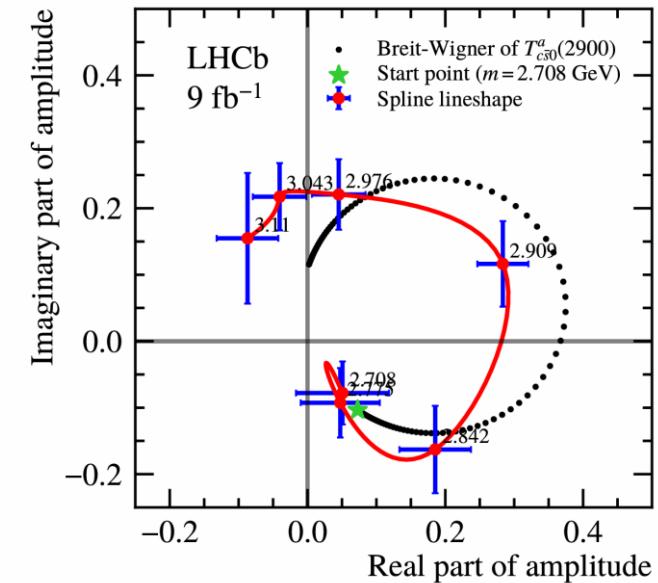
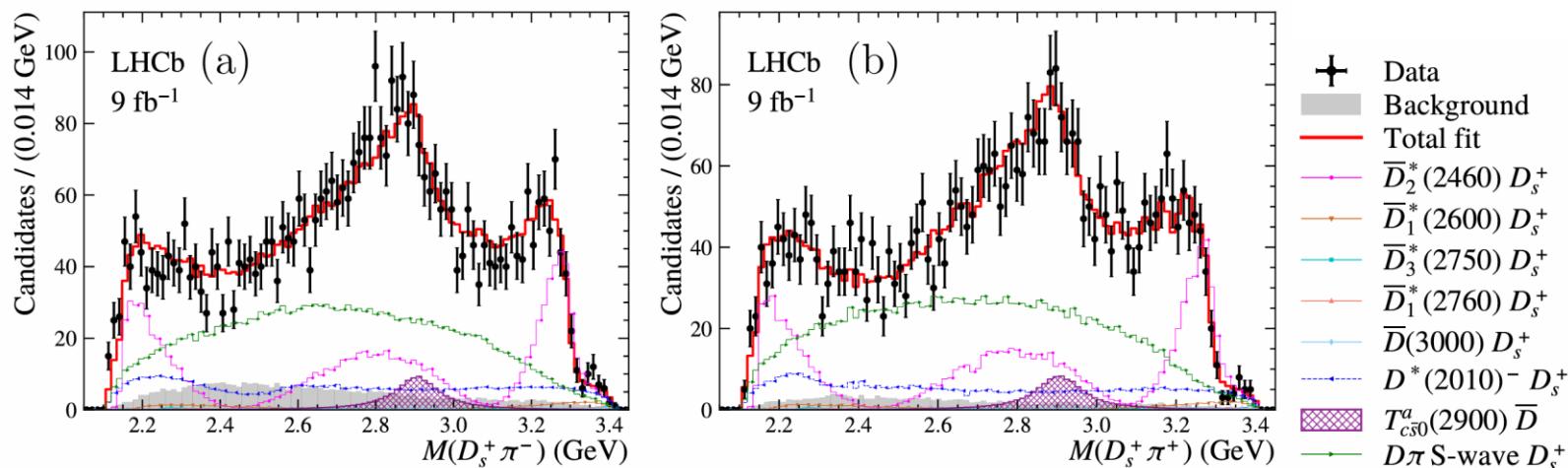
Table 2: Memory requirement for one event



Example: $B^0 \rightarrow \bar{D}^0 D_s^+ \pi^-$, $B^+ \rightarrow D^- D_s^+ \pi^+$

- Constrains with isospin
 - Normal states: $B \rightarrow D^* D_s$, $D^* \rightarrow D\pi$
 - Exotic states: $B \rightarrow DX$, $X \rightarrow D_s\pi$
- New doubly charged tetraquark candidate and its natural partner
 - $T_{c\bar{s}}^a(2900)^{++,0} \rightarrow D_s^+ \pi^\pm$
 - Validation with quasi-model-independent fit
 - Fit with spline model, Argand plot consistent with Breit Wigner circle

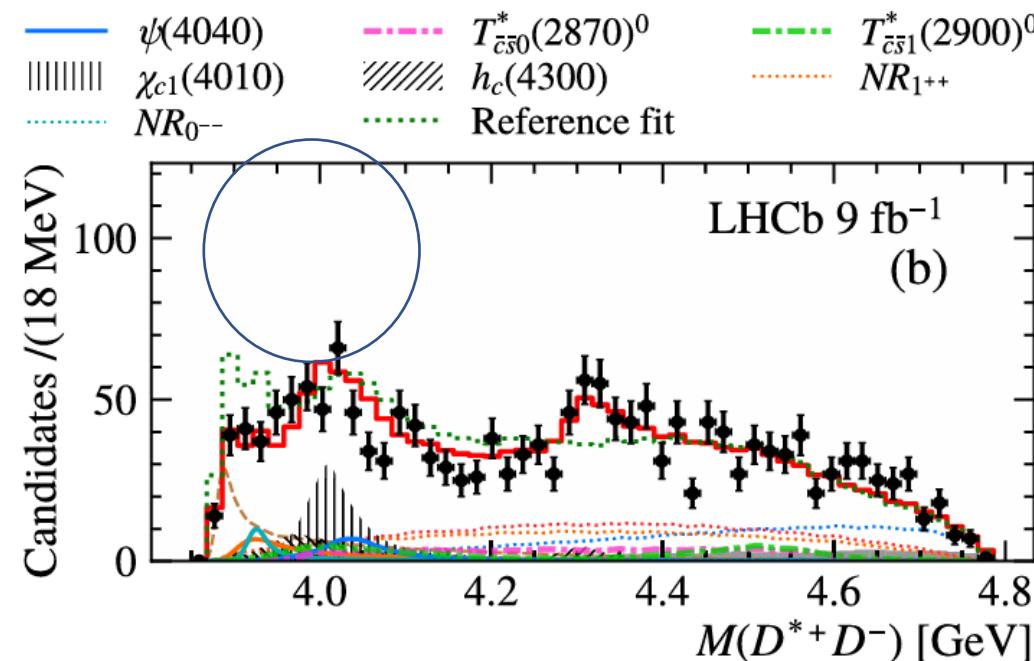
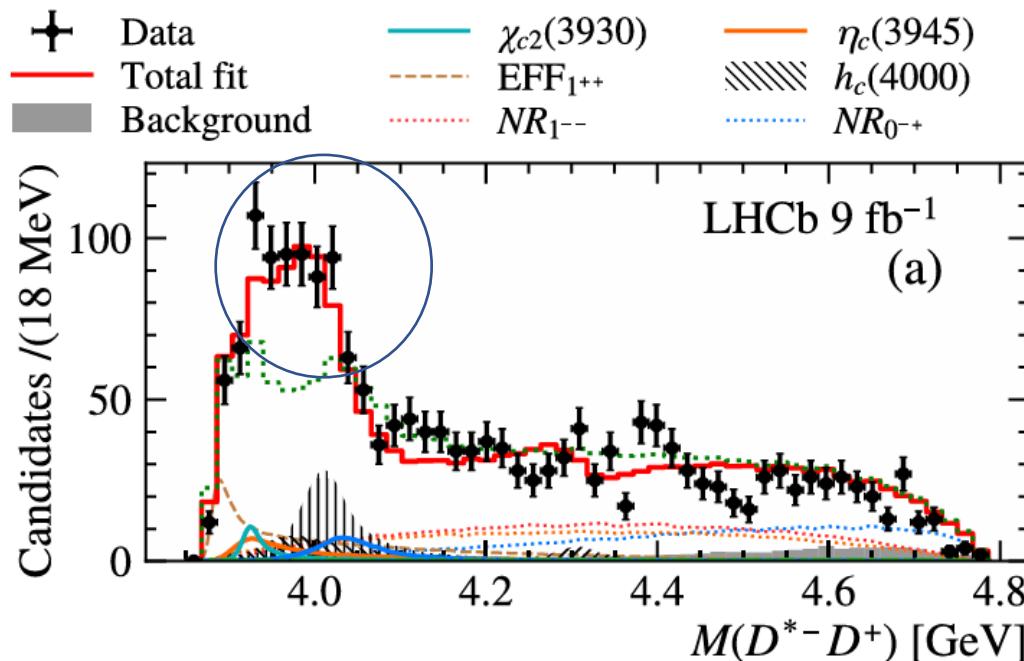
[PRL.131.041902](#)
[PRD.108.012017](#)



Example: $B^+ \rightarrow D^{*\pm} D^\mp K^+$

[PRL.133.131902](#)

- Combine fit with two C-parity related decay channels
 - $B^+ \rightarrow D^{*+} D^- K^+$ and $B^+ \rightarrow D^{*-} D^+ K^+$
 - Constraints: $A(B^+ \rightarrow R \rightarrow (D^{*+} D^-)K^+) = C_R A(B^+ \rightarrow R \rightarrow (D^{*-} D^+)K^+)$
 - Using the interference to describe the difference in $M(D^* D)$
 - Implemented by custom models to deal with extra information (charges)
- Observe new states decay to $D^{*\pm} D^\mp$, and determine its C-parity.



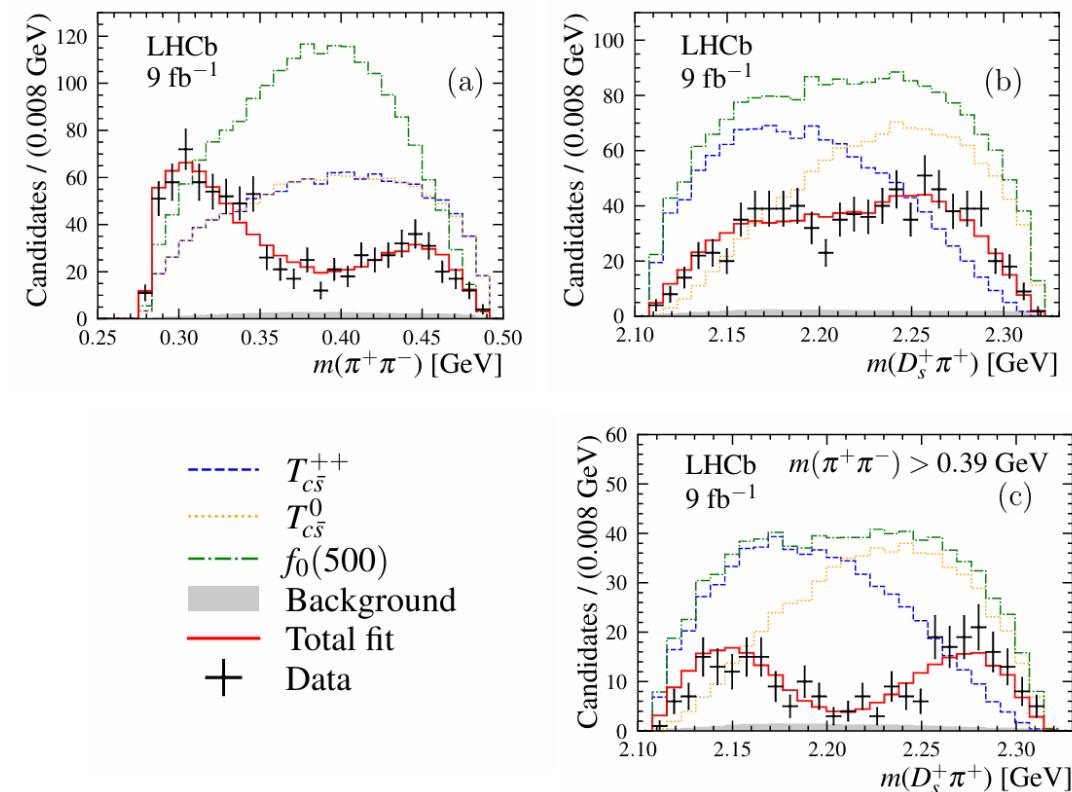
Example: $B \rightarrow D^{(*)}D_{s1}(2460)^+ (\rightarrow D_s^+\pi^+\pi^-)$

[arxiv:2411.03399]

- Simultaneous fit of 3 channels
 - $B^+ \rightarrow \bar{D}^0 D_{s1}(2460)^+, B^0 \rightarrow D^- D_{s1}(2460)^+, B^0 \rightarrow D^{*-} D_{s1}(2460)^+$
 - Share the same model in $D_{s1}(2460)^+ \rightarrow D_s^+\pi^+\pi^-$
- Test of different models
 - Some special models
 - Chiral dynamics

[Commun.Theor.Phys. 75 \(2023\) 5, 055203](#)

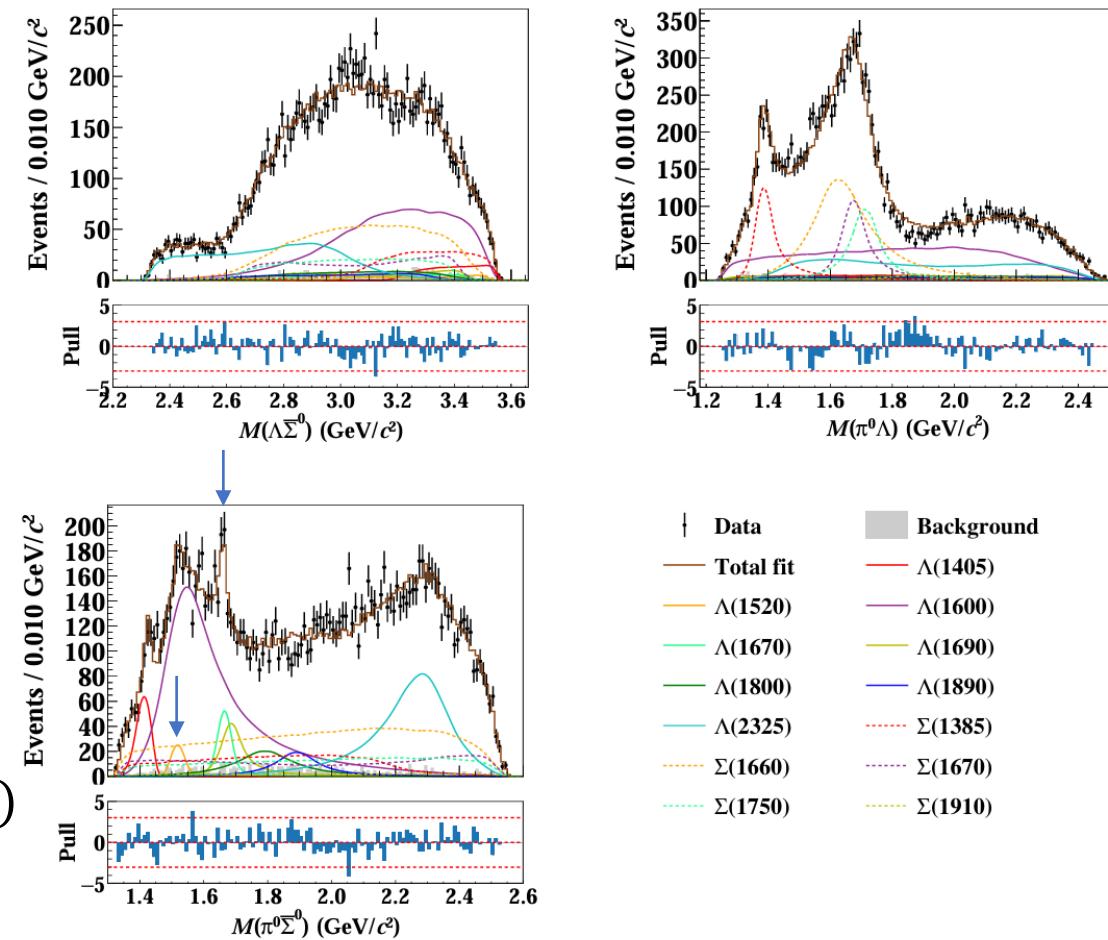
 - predict a double-bump lineshape
 - Implement with interpolation
 - $(\lambda_{D_{s1}}, m, \cos \theta)$
 - K-matrix $T_{c\bar{s}}$ (right plot)
 - $K = \begin{pmatrix} \gamma & \beta \\ \beta & \gamma_2 \end{pmatrix}$
 - $f(m) = \frac{\beta^2 \rho_{DK} + i\gamma_2(i\gamma \rho_{DK} - 1)}{\beta^2 \rho_{DK} \rho_{Ds} \pi + (i\gamma \rho_{DK} - 1)(i\gamma_2(\rho_{Ds} \pi - 1))}$



Example: $\psi(3686) \rightarrow \Lambda\bar{\Sigma}^0\pi^0$

[JHEP 02 \(2025\) 212](#)

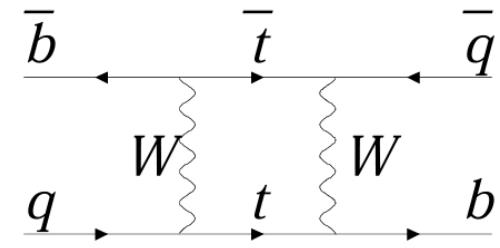
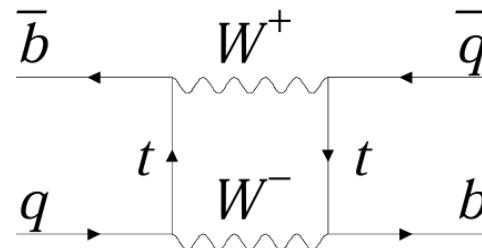
- Double baryon final states
- Consider mass resolution in $M(\pi^0\bar{\Sigma}^0)$
 - Mass resolution: 4.8 MeV
 - Narrow Peak:
 - $\Lambda(1670) \sim 30$ MeV
 - $\Lambda(1520) \sim 20$ MeV
 - $P(m, \cos \theta) \propto |A(m, \cos \theta)|^2 \otimes R(m)$
 - Using numerical integration
 - $m'_k = m + \frac{2k-1}{2N}(\delta_{right} - \delta_{left}) + \delta_{left}$
 - $P(m, \cos \theta) \propto \sum_k |A(m'_k, \cos \theta)|^2 G(m - m'_k)$
 - Plot fit projection
 - Weight with MC truth value $|A(m, \cos \theta)|^2$
 - Plot the distribution of reconstruction masses with weights.



More details of resolution in <https://github.com/jiangyi15/tf-pwa/tree/dev/checks/resolution>

Current progress of TF-PWA

- Time dependent Amplitude (WIP)
 - Time dependence [#168](#) [#179](#)
 - $|B(t)\rangle = g_+(t)|B\rangle + \frac{q}{p}g_-(t)|\bar{B}\rangle$
 - $|\bar{B}(t)\rangle = \frac{p}{q}g_-(t)|B\rangle + g_+(t)|\bar{B}\rangle$
 - Flavour tagging [#183](#)
 - $P(tag, p^\mu, t) = P(tag|B)P(B, p^\mu, t) + P(tag|\bar{B})P(\bar{B}, p^\mu, t)$
 - Production asymmetry [#181](#)
 - $P(B, p^\mu, t) = (1 - A_p)|A(t)|^2, P(\bar{B}, p^\mu, t) = (1 + A_p)|\bar{A}(t)|^2,$
 - Time resolution, [#184](#)
 - $P(B, p^\mu, t) \rightarrow \int P(B, p^\mu, t')R(t - t')dt'$
 - Validations (with LHCb)
- Other related updates on framework



Related project of TF-PWA

- Examples collections
 - Code: <https://github.com/jiangyi15/tf-pwa-example>
 - A collections PWA models
 - Directly using Using TF-PWA
 - Reproduce trough TF-PWA
 - Repeatability of analysis results
 - Provide examples for TF-PWA
- Custom OP for TensorFlow
 - Code: <https://github.com/jiangyi15/tf-pwa-op>
 - To provide faster fuse ops in TensorFlow for PWA
- Interface of EvtGen
 - Code: <https://github.com/jiangyi15/tf-pwa-evtgen>
 - Provide different methods (with and without TensorFlow)
 - Validated in BESEvtGen

Summary

- TF-PWA
 - Convenient configuration, general proposed
 - Use powerful AD in fitting and error propagation.
 - Provide options to achieve high performance
- Some special examples of TF-PWA
- Current development of TF-PWA.

Thank you for your attentions!

Backup

-

Formula of Resolution

- Detector: Combine effect of resolution and efficiency
- An event x was detected as y with probability
 - $p(x \rightarrow y) = \epsilon_x(x)R_x(x \rightarrow y)$
- The real probability of y : $p(y) = \int |A|^2(x)p(x \rightarrow y)dx$
$$\epsilon_y(y) = \int \epsilon_x(x)R_x(x \rightarrow y)dx, R_y(x \rightarrow y) = \frac{p(x \rightarrow y)}{\epsilon_y(y)}$$
$$p(y) = \int |A|^2(x)p(x \rightarrow y)dx = \epsilon_y(y)\int |A|^2(x)R_y(x \rightarrow y)dx$$
- $\epsilon_y(y)$ can be obtained by Phase Space MC. The distribution of reconstructed variables
- $R_y(x \rightarrow y)$ is normalize probability function that y from all possible x .
- Use $R_y(x \rightarrow y)$ to do the convolution,
 - Use phase space MC for flat x , then $R_y(x \rightarrow y)$ is the projection of $p(x, y)$ with fixed y
 - Normalized $\int R_y(x \rightarrow y)dx = 1$.
- Use MC truth to do the integration
 - $\int |A|^2(x)\int \epsilon_y(y)R_y(x \rightarrow y)dydx = \int |A|^2(x)\epsilon_x(x)dx.$

Topology of decay chain

- Define
 - All combination of final particles
- Same
 - Topo: (D, E), (C, D, E)
 - $A \rightarrow R_1 + B, R_1 \rightarrow R_2 + C, R_2 \rightarrow D + E$
 - $A \rightarrow R_3 + B, R_4 \rightarrow R_5 + C, R_5 \rightarrow D + E$
- Not same
 - Topo: (B, C), (D, E)
 - $A \rightarrow R_6 + R_7, R_6 \rightarrow B + C, R_7 \rightarrow D + E$

Factor system: automatic factorization of amplitude

- Amplitude can be written as the combination of summation and production.

$$A = (\sum g_i A_i) (\sum g'_j A'_j) \cdots \Rightarrow A = \sum_{ij} (g_i g'_j) (A_i A'_j)$$

$$G_{(i,j)} = g_i g'_j = \begin{cases} 1 & i,j = (a,b) \\ 0 & i,j \neq (a,b) \end{cases} \Rightarrow A = B_{(i,j)} = A_i A'_j$$

- No need known for the exact formula A_i , just use the parameters g_i .
- Some special treatment is implemented as option for better performances. (comparing in [Page 21](#))
 - Amplitude caching method
 - mass dependent:
 - $A(p_i^\mu) = \sum g_i R(m) A_i(p_i^\mu) \Rightarrow A(m) = \sum g_i R(m) B_i$
 - factor only: (only for MC integration)
 - $\sum |A|^2 \rightarrow G_i G_j^* (\sum C_{ij})$ calculate only once
 - Required all shape parameters fixed
 - Special in simultaneous fit
 - Mixed likelihood, avoid small size data

Add control options,
base on the same structure,
we can extract it automatically

$$-\ln L_1 - \ln L_2 = -\sum_{data1+data2} \ln|A|^2 + N_1 \ln \sum_{mc1} |A|^2 + N_2 \ln \sum_{mc2} |A|^2$$

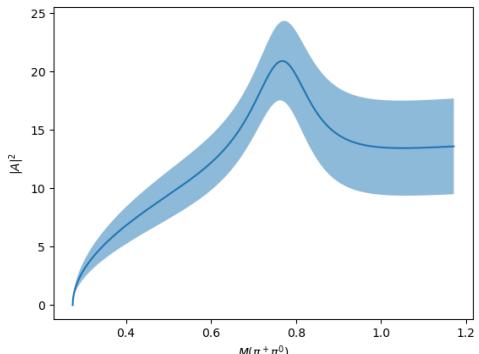
Amplitude as a function

- Reverse process of angle calculation
 - Mass + Helicity angle -> 4-momenta
 - $(m_0, \phi_0, \theta_0, m_{12}, \phi_{12}, \theta_{12}) \xrightarrow{\text{transform}} p_1^\mu, p_2^\mu, p_3^\mu$
- Factor system:
 - Eval amplitude of special partial wave though control of parameters
 - $A(p_1^\mu, p_2^\mu, p_3^\mu) \xrightarrow{g_{i \neq j} = 0} g_i A_i(p_1^\mu, p_2^\mu, p_3^\mu)$
- Combine Together: Lineshape function of special wave
 - Set angle to 0, $D_{m,m'}(0,0,0) = \delta_{m,m'}$ is constant.
 - Vary mass, then get the shape of masses
 - $f(m_{12}) = g_i A_i (m_0, \phi_0 = 0, \theta_0 = 0, m_{12}, m_{12}, \phi_{12} = 0, \theta_{12} = 0)$
 - No worries for the complex formula
- 2D function of amplitude
 - 2D plot Dalitz variables
 - 2D plot of Mass and $\cos \theta$

```
f1 = config.get_particle_function("R1")
f2 = config.get_particle_function("R2")

m = f1.mass_linspace(1000)
# plot the first wave
amp = tf.abs(f1(m)[:,0] + f2(m)[:,0])**2
plt.plot(m, amp)
```

Uncertainties from error propagation



Custom Model

Line: $R(M; a) = M + a$

```
from tf_pwa.amp import register_particle
from tf_pwa.amp import Particle

@register_particle("Line")
class LineModel(Particle):

    def init_params(self): # define parameters
        self.a = self.add_var("a")

    def get_amp(self, *args, **kwargs):
        """ model as m + a """
        m = args[0]["m"]
        zeros = tf.zeros_like(m)
        return tf.complex(m + self.a(), zeros)
```

Define a custom model is very simple.

$$H_{[\lambda_R \lambda_B]}(x; \vartheta) D_{[\lambda_A, \lambda_R - \lambda_B]}^{j_A \star}(x) R(x; \vartheta) H_{[\lambda_C \lambda_D]}(x; \vartheta) D_{[\lambda_R, \lambda_C - \lambda_D]}^{j_R \star}(x) \\ D_{[\lambda_B, \lambda'_B]}^{j_B \star}(x) D_{[\lambda_C, \lambda'_C]}^{j_C \star}(x) D_{[\lambda_D, \lambda'_D]}^{j_D \star}(x) \rightarrow A_{[\lambda_A, \lambda'_B, \lambda'_C, \lambda'_D]}(x; \vartheta) \\ \lambda_{[RB][ARB][][CD][RCD][BB'][cc'][DD']} \rightarrow [AB'C'D']$$

The shape is (number of events,), type is complex128

$R(x; \vartheta)$ {
 x : all data, (*args, **kwargs)
 ϑ : all parameters (self.a , ...)

here the data, (*args, **kwargs) is passed from DecayChain.

For convenience, different data will be divided into different parts to pass to `get_amp(self, *args, **kwargs)`

The parameters are directly defined in the class, and the values are obtained from `VarsManager`.

Use `register_particle` to register it, then it can be used in config.yml

Alignment angle in TFPWA for helicity formula

Boost: $B_z(\omega)$, Rotation: $R_z(\phi), R_y(\theta)$

For final state $|out\rangle = |p_1\rangle \otimes |p_2\rangle \otimes |p_3\rangle$, choose a single particle state $|p_1\rangle$.

The final state define in $0 \rightarrow R, 2; R \rightarrow 1, 3$:

$$|p_1\rangle_R = B_z(\omega_1)R_z(0)R_y(\theta_1)R_z(\phi_1)|p_1\rangle = L_1|p_1\rangle$$

$$|p_1\rangle_1 = B_z(\omega_2)R_z(0)R_y(\theta_2)R_z(\phi_2)|p_1\rangle = L_2|p_1\rangle_R$$

On the other decay chain $0 \rightarrow R', 3; R' \rightarrow 1, 2$:

$$|p_1\rangle_{R'} = B_z(\omega'_1)R_z(0)R_y(\theta'_1)R_z(\phi'_1)|p_1\rangle = L'_1|p_1\rangle$$

$$|p_1\rangle_2 = B_z(\omega'_2)R_z(0)R_y(\theta'_2)R_z(\phi'_2)|p_1\rangle = L'_2|p_1\rangle_{R'}$$

The final state is the rest frame, so no boost remained.

The alignment angle is the rotation

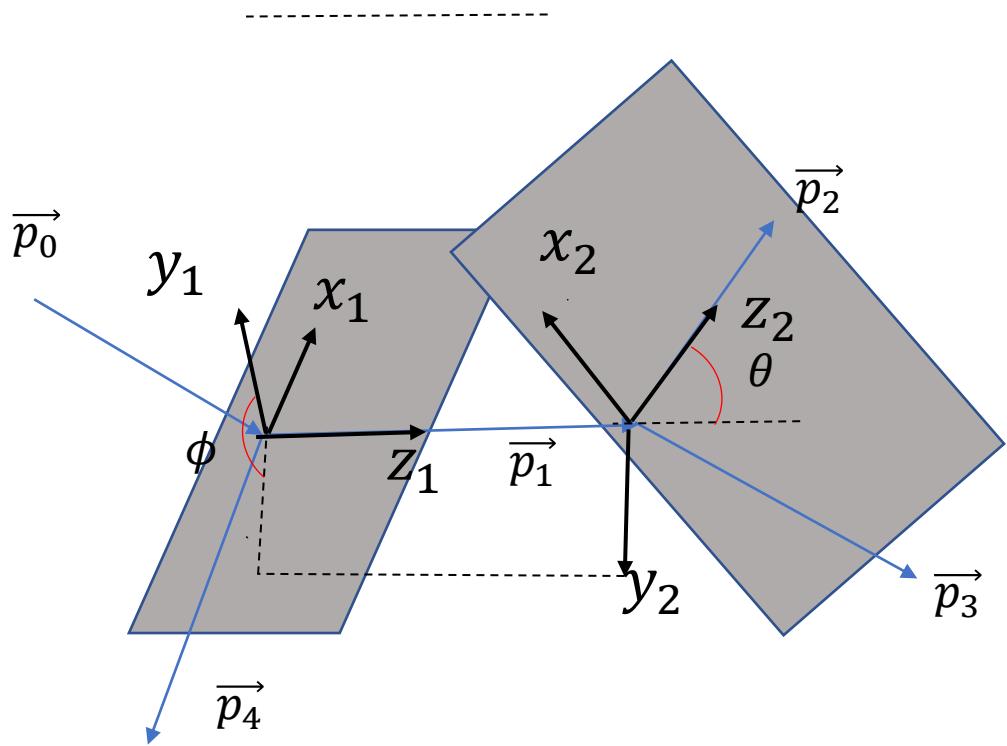
$$|p_1\rangle_2 = L_r|p_1\rangle_1 = R_z(\gamma)R_y(\beta)R_z(\alpha)|p_1\rangle_1$$

So

$$L_r = R_z(\gamma)R_y(\beta)R_z(\alpha) = L'_2 L'_1 L_1^{-1} L_2^{-1}$$

In general

$$L_r = L_a L_b^{-1} = \left(\prod_i L'_{n-i} \right) \left(\prod_j L_j^{-1} \right)$$



choose SU(2) representation as

$$\omega = \text{arccosh} \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} \quad B_z(\omega) = \begin{pmatrix} e^{-\frac{\omega}{2}} & 0 \\ 0 & e^{\frac{\omega}{2}} \end{pmatrix}, R_z(\phi) = \begin{pmatrix} e^{-\frac{i\phi}{2}} & 0 \\ 0 & e^{\frac{i\phi}{2}} \end{pmatrix}, R_y(\theta) = \begin{pmatrix} \cos \frac{\beta}{2} & -\sin \frac{\beta}{2} \\ \sin \frac{\beta}{2} & \cos \frac{\beta}{2} \end{pmatrix}$$

$$L_{ab} = R_z(\gamma)R_y(\beta)R_z(\alpha) = \begin{pmatrix} \cos \frac{\beta}{2} e^{-\frac{i(\alpha+\gamma)}{2}} & -\sin \frac{\beta}{2} e^{\frac{i(\alpha-\gamma)}{2}} \\ \sin \frac{\beta}{2} e^{-\frac{i(\alpha-\gamma)}{2}} & \cos \frac{\beta}{2} e^{\frac{i(\alpha+\gamma)}{2}} \end{pmatrix}$$

$$\cos \beta = \cos^2 \frac{\beta}{2} - \sin^2 \frac{\beta}{2} = L_{11}L_{22} + L_{12}L_{21}, \beta \in [0, \pi]$$

$$\alpha + \gamma = -2 \text{ ang } L_{11} = 2 \text{ ang } L_{22}, \alpha - \gamma = -2 \text{ ang } L_{12} = -2 \text{ ang } L_{21}$$

$$|L_{ab}| = 1 \quad L_{ab}^{-1} = \begin{pmatrix} L_{22} & -L_{12} \\ -L_{21} & L_{11} \end{pmatrix}$$

Simple AD implement

- backward AD

```
Var a = Var(3.1415926);
auto b = SinOp(&a);
auto c = AddOp(&a, &b);
c.backward(1.0);
std::cout<< a.grad;
```

Output: 1.44329e-15

$$\begin{aligned}x + \sin x \\ grad(Add, Var) \\ grad(Var, x) \\ +grad(Add, \sin(x)) \\ grad(\sin(x), Var) \\ grad(Var, x)\end{aligned}$$

$\approx 1 + \cos \pi$

- have to use **defined Op**
- caching** forward results,
 - improve the speed
 - more memory required
- Vectorized:
 - single operator, multiple data
 - optimized for linear algebra

```
#include<cmath>
#include<vector>
class Op {
    public: std::vector<Op*> inputs;
    virtual double forward() = 0;
    virtual void backward(double grad=1) = 0;
};

class Var: public Op {
    public: double value, grad;
    Var(double value): value(value), grad(0.) {inputs={};}
    double forward() override { return value; }
    void backward(double grad=1) override {
        this->grad += grad;
    }
};

class SinOp: public Op {
    public: SinOp(Op* input) {inputs = {input};}
    double forward() override {
        return sin(inputs[0]->forward());
    }
    void backward(double grad=1) override {
        inputs[0]->backward(grad * cos(inputs[0]->forward()));
    }
};

class AddOp: public Op {
    public: AddOp(Op* x, Op* y) {inputs = {x, y};}
    double forward() override {
        return inputs[0]->forward() + inputs[1]->forward();
    }
    void backward(double grad=1) override {
        inputs[0]->backward(grad);
        inputs[1]->backward(grad);
    }
};
```

Likelihood formula

- Option in config.yml: data: model
- Default

- $-\ln L = -\sum_{i \in data} w_i \ln|A|^2(x_i) + (\sum_{i \in data} w_i) \ln I_{sig}$
- $I_{sig} = \frac{\sum_{j \in MC} \omega_j |A|^2(x_j)}{\sum_{j \in MC} \omega_j}$

- bg will be merged into data with -weights

- cfit:
 - Additional information data:
 - bg_value for value of bg
 - Additional config
 - bg_frac: f_{bg}

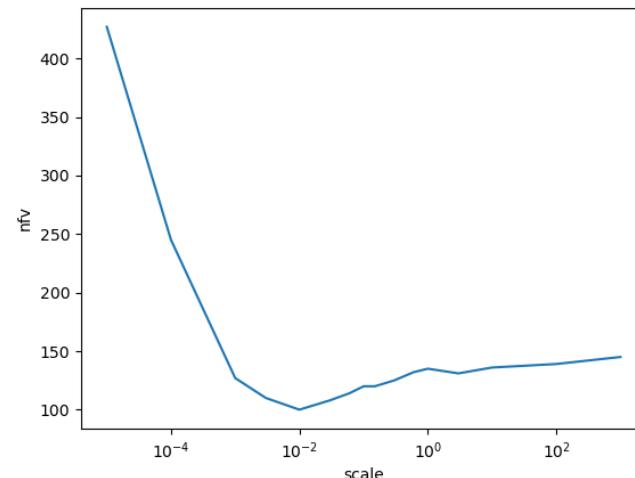
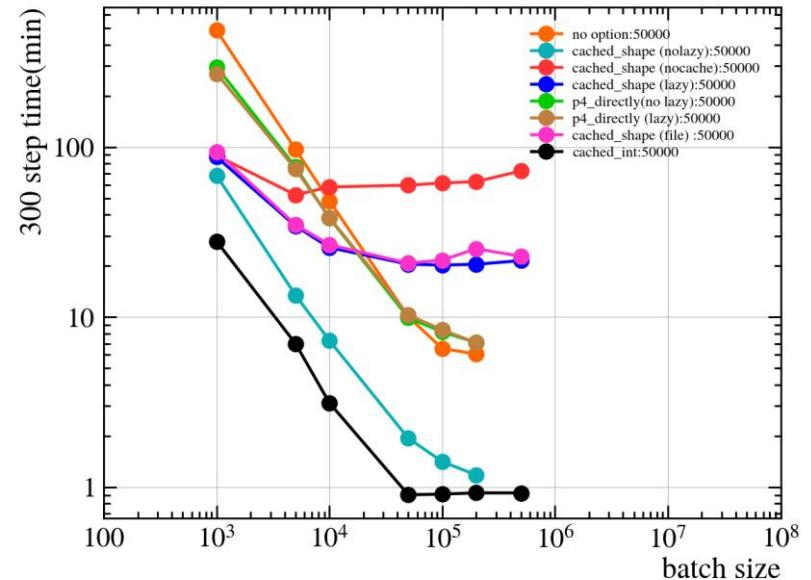
- $-\ln L(\vartheta) = -\sum \ln \left[(1 - f_{bg}) \frac{|A|^2(x; \vartheta)}{I_{sig}} + f_{bg} \frac{B(x; \vartheta)}{I_B} \right]$

```
data:  
  dat_order: [B, C, D]  
  data: [data.dat]  
  bg: [bg.dat]  
  bg_weight: 0.1  
  phsp: [phsp.dat]
```

```
data:  
  dat_order: [B, C, D]  
  model: cfit  
  bg_frac: 0.1  
  data: [data.dat]  
  data_bg_value: [data_bgv.dat]  
  phsp: [phsp.dat]  
  phsp_bg_value: [phsp_bgv.dat]
```

Other option affecting fit time

- Batch size : config.fit(batch=n)
 - Batch for calculating gradient
 - Large is better but required large memory
- tf.function: use_tf_function
 - Compile function to reduce python operation
 - Add no_id_cached: True when use lazy_call
 - Additional jit_compile
 - Required additional memory and setup time
- Grad scale: config.fit(grad_scale=x)
 - Can reduce iterations to best minimal



Batch for Hessian

- $\frac{\partial \ln L(\vartheta)}{\partial \vartheta} = \frac{\partial \ln L(\vartheta, I)}{\partial \vartheta} + \frac{\partial \ln L(\vartheta, I)}{\partial I} \frac{\partial I}{\partial \vartheta}$
- $\frac{\partial^2 \ln L(\vartheta)}{\partial \vartheta \partial \vartheta} = \left[\frac{\partial^2 \ln L(\vartheta, I)}{\partial \vartheta \partial \vartheta} + \frac{\partial^2 \ln L(\vartheta, I)}{\partial \vartheta \partial I} \frac{\partial I}{\partial \vartheta} \right] + \left(\frac{\partial^2 \ln L(\vartheta, I)}{\partial I \partial \vartheta} \frac{\partial I}{\partial \vartheta} + \frac{\partial^2 \ln L(\vartheta, I)}{\partial I \partial I} \frac{\partial I}{\partial \vartheta} \frac{\partial I}{\partial \vartheta} \right) + \frac{\partial \ln L(\vartheta, I)}{\partial I} \frac{\partial^2 I}{\partial \vartheta \partial \vartheta}$
- Step1: eval $(I, \frac{\partial I}{\partial \vartheta}, \frac{\partial^2 I}{\partial \vartheta \partial \vartheta})$ in small batch
- Step2: eval $(\ln L(\vartheta'), \frac{\partial \ln L(\vartheta')}{\partial \vartheta'}, \frac{\partial \ln L(\vartheta')}{\partial \vartheta' \partial \vartheta'})$ in small batch
 - Here: $\vartheta'_i = (\vartheta_i, I), \frac{\partial \vartheta'_i}{\partial \vartheta_j} = (\delta_{ij}, \frac{\partial I}{\partial \vartheta_j})$
- Step3: $\frac{\partial^2 \ln L(\vartheta)}{\partial \vartheta_i \partial \vartheta_j} = \frac{\partial^2 \ln L(\vartheta')}{\partial \vartheta'_k \partial \vartheta'_l} \frac{\partial \vartheta'_k}{\partial \vartheta_i} \frac{\partial \vartheta'_l}{\partial \vartheta_j} + \frac{\partial^2 \ln L(\vartheta')}{\partial I} \frac{\partial^2 I}{\partial \vartheta_i \partial \vartheta_j}$

Different location for preprocess data

- No cached

```
data:  
...  
lazy_call: True
```

- GPU vRAM

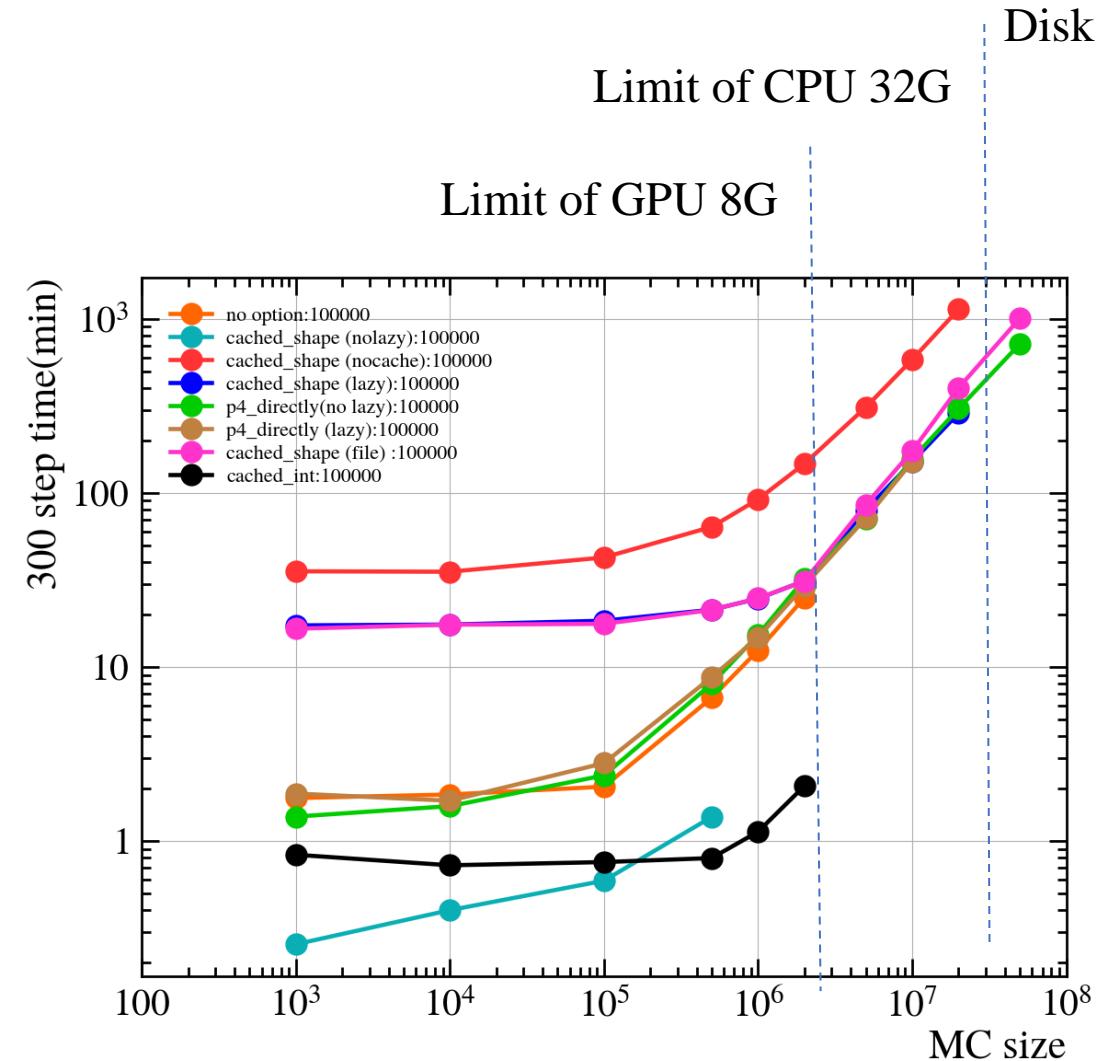
- No addition option

- CPU RAM

```
data:  
...  
lazy_call: True  
cached_lazy_file: ""
```

- Disk

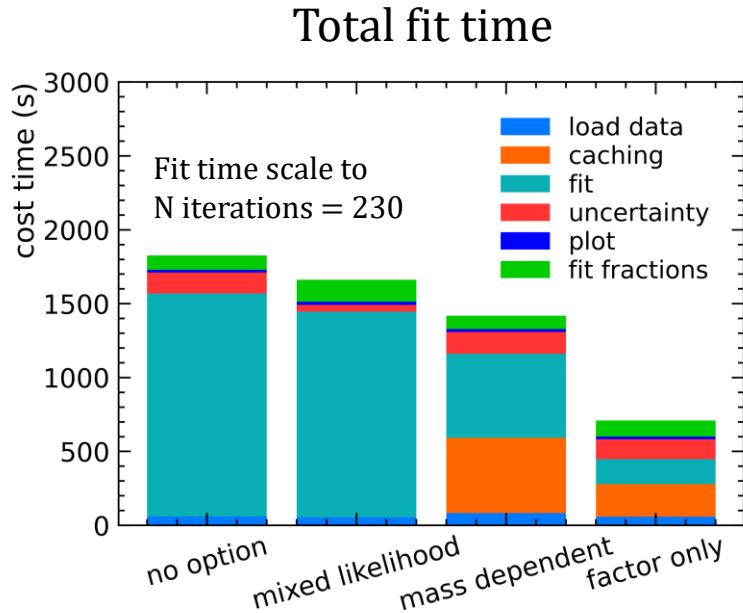
```
data:  
...  
lazy_call: True  
cached_lazy_file: dir_of_files/
```



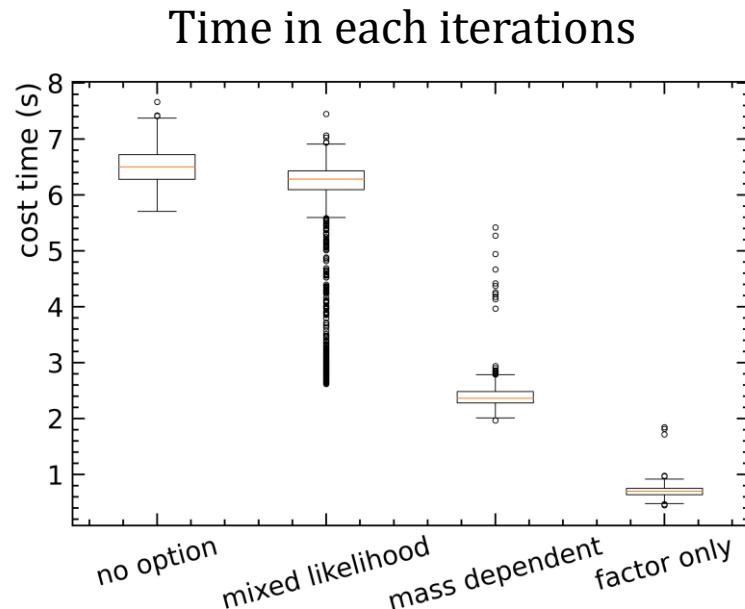
Real analysis performance

Environment:
NVIDIA RTX 3080
TensorFlow 2.2
CUDA 10.1

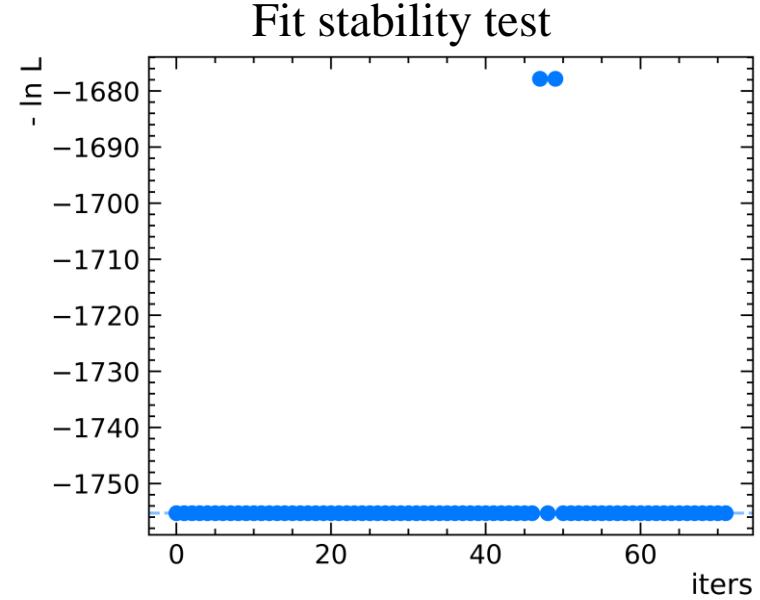
- Optimized method in Factor System page
 - Caching method
 - Large time for caching
 - required more memory
 - limited to special cases
 - All the process is automatic (from config.yml to all basic results)



Only half of hours
for **ALL** the process



Caching provide 8 times speed up
for fit parts



Fit stability looks well
in random initial parameters **36**