

Interpolating Instant and Light-Front Dynamics

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Outline

- **Conformal Symmetry Nature of Spacetime**
- **1+1 Dimensional Conformal Algebra**
- **Interpolation between IFD and LFD**
- **Orientation Entanglement in Relativistic Helicity**
- **Critical Point Appearance between IFD and LFD**
- **'t Hooft model as a toy QCD**
- **Link to the Light-Front Quark Model**
- **Phenomenological Application of LFQM**
- **Conclusions and Outlook**

Conformal Transformation of Spacetime

$$\frac{\partial x'^{\alpha}}{\partial x^{\mu}} \frac{\partial x'^{\beta}}{\partial x^{\nu}} g'_{\alpha\beta} = \Lambda(x) g_{\mu\nu}$$

Conformal Generators

$P_{\mu} = i\partial_{\mu}$	(translation)
$M_{\mu\nu} = i(x_{\mu}\partial_{\nu} - x_{\nu}\partial_{\mu})$	(rotation)
$D = ix_{\mu}\partial^{\mu}$	(dilation)
$\mathfrak{K}_{\mu} = i(2x_{\mu}x_{\nu}\partial^{\nu} - x^2\partial_{\mu})$	(SCT)

In 0-space and 1-time (0 + 1) dimension,

Möbius transformation $x_0 \rightarrow x'_0 = \frac{\alpha x_0 + \beta}{\gamma x_0 + \delta}$, $\text{Det} \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} = 1$

$$P_0^{(0+1)} = i\sigma_- = \begin{pmatrix} 0 & 0 \\ i & 0 \end{pmatrix},$$

V. de Alfaro, S. Fubini, and G. Furlan, Conformal invariance in quantum mechanics, *Il Nuovo Cimento A* (1965-1970) **34**, 569 (1976).

$$D_0^{(0+1)} = \frac{i}{2}\sigma_3 = \begin{pmatrix} \frac{i}{2} & 0 \\ 0 & -\frac{i}{2} \end{pmatrix},$$

$$P_0^{(0+1)} = i\partial_0,$$

$$D_0^{(0+1)} = ix_0\partial_0,$$

$$\mathfrak{K}_0^{(0+1)} = -i\sigma_+ = \begin{pmatrix} 0 & -i \\ 0 & 0 \end{pmatrix},$$

$$\mathfrak{K}_0^{(0+1)} = ix_0x_0\partial_0.$$

where $\sigma_{\pm} = \frac{\sigma_1 \pm i\sigma_2}{2}$.

S. J. Brodsky, G. F. de Téramond, H. G. Dosch, and J. Erlich, Light-front holographic QCD and emerging confinement, *Phys. Rep.* **584**, 1 (2015).

Anti de-Sitter space (AdS₂)

In 1-space and 0-time (1+0) dimension,

Möbius transformation

$$x_3 \rightarrow x'_3 = \frac{\alpha x_3 + \beta}{\gamma x_3 + \delta}, \quad \text{Det} \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} = 1$$

$$P_3^{(1+0)} = i\sigma_- = \begin{pmatrix} 0 & 0 \\ i & 0 \end{pmatrix},$$

**C.Ji & H. Ravikumar,
PRD113, 096018 (2026).**

$$P_3^{(1+0)} = i\partial_3,$$

$$D_3^{(1+0)} = \frac{i}{2}\sigma_3 = \begin{pmatrix} \frac{i}{2} & 0 \\ 0 & -\frac{i}{2} \end{pmatrix},$$

$$P_3^{(1+0)} = i \frac{(a^\dagger - a)}{\sqrt{2}},$$

$$D_3^{(1+0)} = -ix_3\partial_3.$$

$$\mathfrak{R}_3^{(1+0)} = +i\sigma_+ = \begin{pmatrix} 0 & i \\ 0 & 0 \end{pmatrix},$$

$$D_3^{(1+0)} = \frac{-i}{2}(a^{\dagger 2} - a^2 + 1),$$

$$\mathfrak{R}_3^{(1+0)} = -ix_3x_3\partial_3,$$

$$\mathfrak{R}_3^{(1+0)} = \frac{-i}{2\sqrt{2}}(3a + 3a^\dagger + a^{\dagger 2}a - a^3 + a^{\dagger 3} - a^2a^\dagger).$$

$$i\sigma_- \leftrightarrow i \frac{(a^\dagger - a)}{\sqrt{2}},$$

$$i\sigma_+ \leftrightarrow \frac{-i}{2\sqrt{2}} (3a + 3a^\dagger + a^{\dagger 2}a - a^3 + a^{\dagger 3} - a^2a^\dagger),$$

$$\frac{i}{2}\sigma_3 \leftrightarrow \frac{-i}{2} (a^{\dagger 2} - a^2 + 1).$$

0 + 1 conformal algebra

	$\mathfrak{K}_0^{(0+1)}$	$P_0^{(0+1)}$	$D_0^{(0+1)}$
$\mathfrak{K}_0^{(0+1)}$	0	$-2iD_0^{(0+1)}$	$-i\mathfrak{K}_0^{(0+1)}$
$P_0^{(0+1)}$	$2iD_0^{(0+1)}$	0	$iP_0^{(0+1)}$
$D_0^{(0+1)}$	$i\mathfrak{K}_0^{(0+1)}$	$-iP_0^{(0+1)}$	0

1 + 0 conformal algebra

	$\mathfrak{K}_3^{(1+0)}$	$P_3^{(1+0)}$	$D_3^{(1+0)}$
$\mathfrak{K}_3^{(1+0)}$	0	$2iD_3^{(1+0)}$	$-i\mathfrak{K}_3^{(1+0)}$
$P_3^{(1+0)}$	$-2iD_3^{(1+0)}$	0	$iP_3^{(1+0)}$
$D_3^{(1+0)}$	$i\mathfrak{K}_3^{(1+0)}$	$-iP_3^{(1+0)}$	0

CONFORMAL ALGEBRA IN (1 + 1) DIMENSIONS

$$P_0^{(1+1)} = i\partial_0,$$

$$\mathfrak{K}_0^{(1+1)} = i(x_0x_0\partial_0 - 2x_3x_0\partial_3 + x_3x_3\partial_0),$$

$$D^{(1+1)} = ix_0\partial_0 - ix_3\partial_3,$$

$$P_3^{(1+1)} = i\partial_3,$$

$$\mathfrak{K}_3^{(1+1)} = -i(x_3x_3\partial_3 - 2x_0x_3\partial_0 + x_0x_0\partial_3),$$

$$K_3^{(1+1)} = -i(x_3\partial_0 - x_0\partial_3).$$

$$P_0^{(1+1)} = P_0^{(0+1)},$$

$$D^{(1+1)} = D_0^{(0+1)} + D_3^{(1+0)},$$

$$P_3^{(1+1)} = P_3^{(1+0)}.$$

$$K_3^{(1+1)} = -i(x_3\partial_0 - x_0\partial_3).$$

$$\mathfrak{R}_0^{(1+1)} = \mathfrak{R}_0^{(0+1)} - x_3K_3^{(1+1)} - x_3x_0P_3^{(1+0)},$$

$$\mathfrak{R}_3^{(1+1)} = \mathfrak{R}_3^{(1+0)} - x_0K_3^{(1+1)} + x_3x_0P_0^{(0+1)},$$

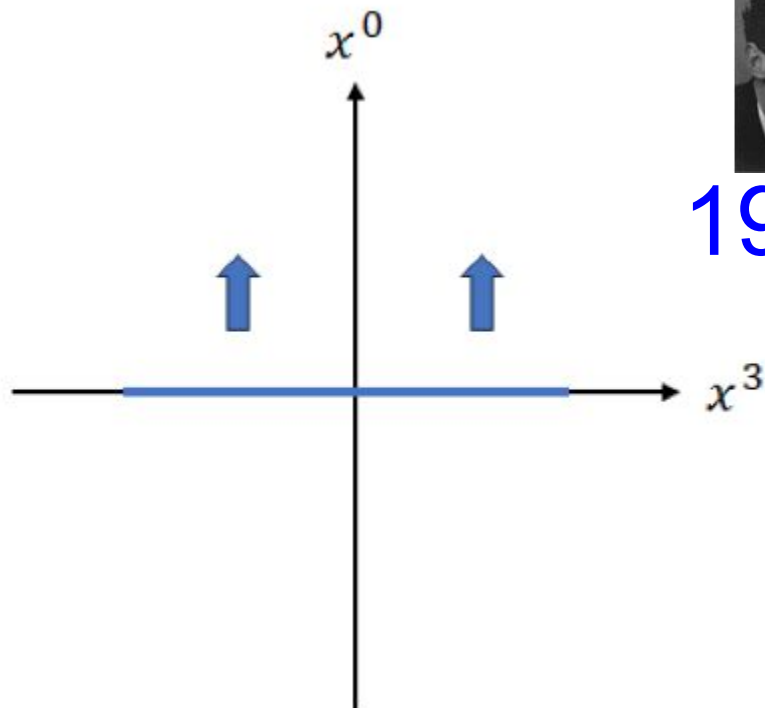
1 + 1 conformal algebra.

	\mathfrak{K}_0	P_0	D	\mathfrak{K}_3	P_3	K_3
\mathfrak{K}_0	0	$-2iD$	$-i\mathfrak{K}_0$	0	$-2iK_3$	$i\mathfrak{K}_3$
P_0	$2iD$	0	iP_0	$-2iK_3$	0	iP_3
D	$i\mathfrak{K}_0$	$-iP_0$	0	$i\mathfrak{K}_3$	$-iP_3$	0
\mathfrak{K}_3	0	$2iK_3$	$-i\mathfrak{K}_3$	0	$2iD$	$i\mathfrak{K}_0$
P_3	$2iK_3$	0	iP_3	$-2iD$	0	iP_0
K_3	$-i\mathfrak{K}_3$	$-iP_3$	0	$-i\mathfrak{K}_0$	$-iP_0$	0

Dirac's Proposition for Relativistic Dynamics

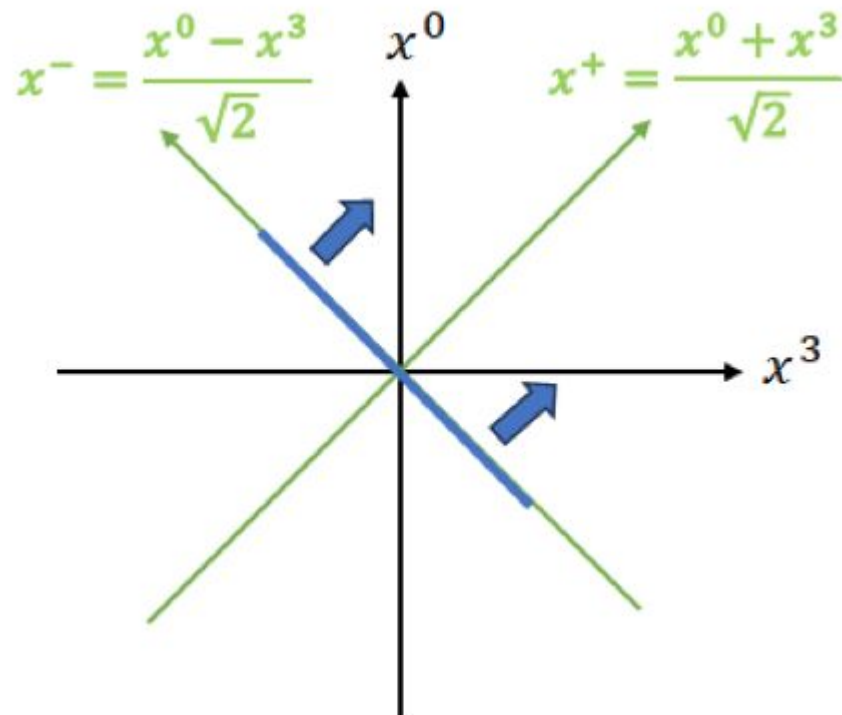


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IFD

Instant Form Dynamics



LFD

Light-Front Dynamics

LFD

$$P_{\pm} = \frac{P_0 \pm P_3}{\sqrt{2}}, \quad \mathfrak{R}_{\pm} = \frac{\mathfrak{R}_0 \mp \mathfrak{R}_3}{\sqrt{2}}, \quad \text{and} \quad D_{\pm} = \frac{D \mp K^3}{\sqrt{2}}$$

	\mathfrak{R}_+	P_+	D_+	\mathfrak{R}_-	P_-	D_-
\mathfrak{R}_+	0	$-2\sqrt{2}iD_+$	$-\sqrt{2}i\mathfrak{R}_+$	0	0	0
P_+	$2\sqrt{2}iD_+$	0	$\sqrt{2}iP_+$	0	0	0
D_+	$\sqrt{2}i\mathfrak{R}_+$	$-\sqrt{2}iP_+$	0	0	0	0
\mathfrak{R}_-	0	0	0	0	$-2\sqrt{2}iD_-$	$-\sqrt{2}i\mathfrak{R}_-$
P_-	0	0	0	$2\sqrt{2}iD_-$	0	$\sqrt{2}iP_-$
D_-	0	0	0	$\sqrt{2}i\mathfrak{R}_-$	$-\sqrt{2}iP_-$	0

$$P_\mu = i\partial_\mu \quad (\text{translation})$$

$$M_{\mu\nu} = i(x_\mu\partial_\nu - x_\nu\partial_\mu) \quad (\text{rotation})$$

$$D = ix_\mu\partial^\mu \quad (\text{dilation})$$

$$\mathfrak{K}_\mu = i(2x_\mu x_\nu\partial^\nu - x^2\partial_\mu) \quad (\text{SCT})$$

**C.Ji & H. Ravikumar,
PRD113, 096018 (2026)**

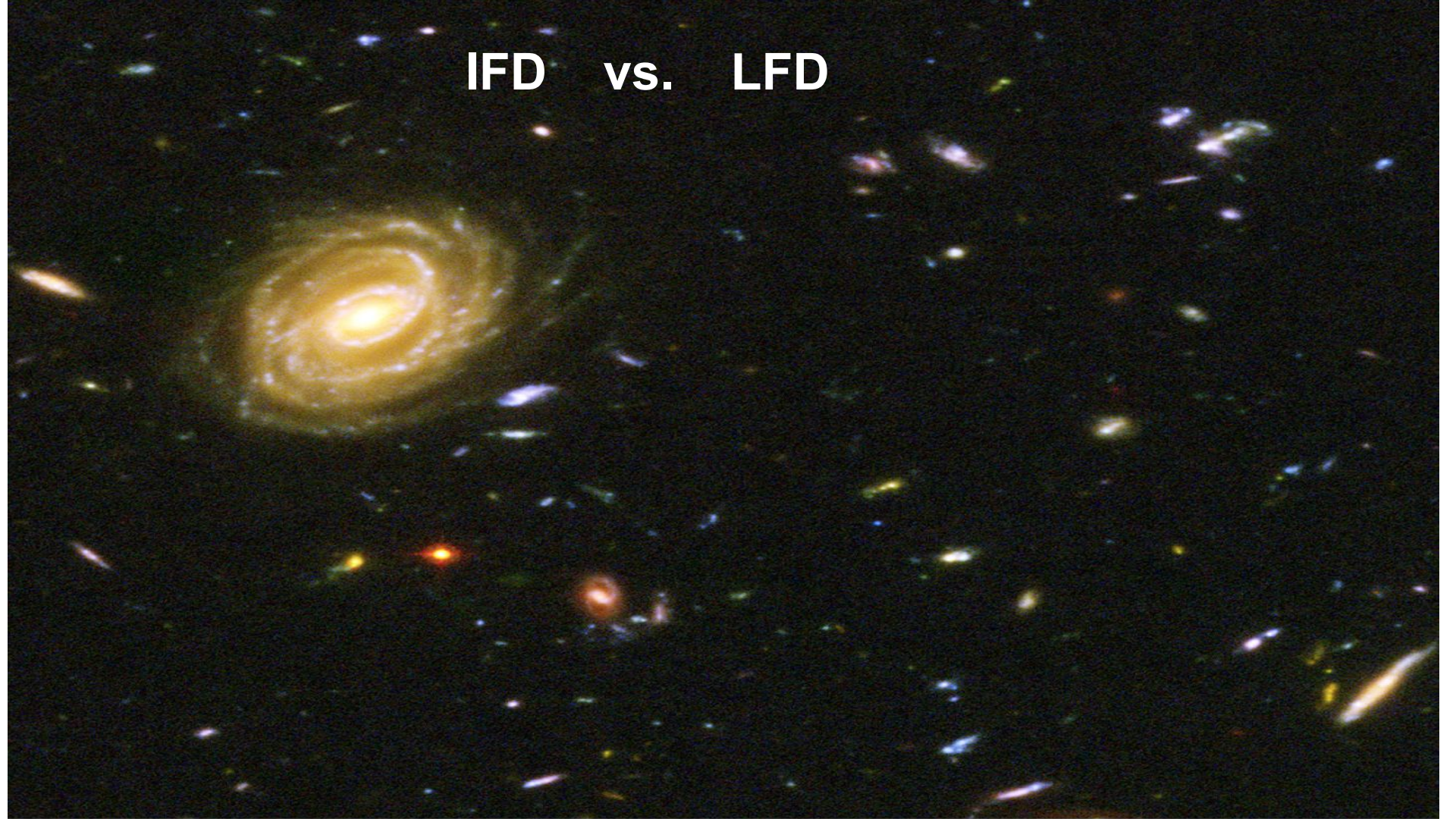
1 + 1 conformal algebra in IFD

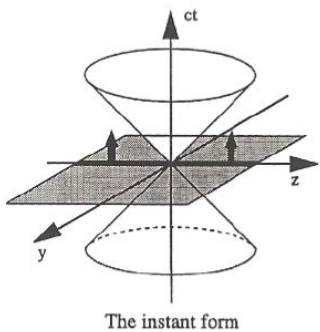
	\mathfrak{K}_0	P_0	D	\mathfrak{K}_3	P_3	K_3
\mathfrak{K}_0	0	$-2iD$	$-i\mathfrak{K}_0$	0	$-2iK_3$	$i\mathfrak{K}_3$
P_0	$2iD$	0	iP_0	$-2iK_3$	0	iP_3
D	$i\mathfrak{K}_0$	$-iP_0$	0	$i\mathfrak{K}_3$	$-iP_3$	0
\mathfrak{K}_3	0	$2iK_3$	$-i\mathfrak{K}_3$	0	$2iD$	$i\mathfrak{K}_0$
P_3	$2iK_3$	0	iP_3	$-2iD$	0	iP_0
K_3	$-i\mathfrak{K}_3$	$-iP_3$	0	$-i\mathfrak{K}_0$	$-iP_0$	0

1 + 1 conformal algebra in LFD

	\mathfrak{K}_+	P_+	D_+	\mathfrak{K}_-	P_-	D_-
\mathfrak{K}_+	0	$-2\sqrt{2}iD_+$	$-\sqrt{2}i\mathfrak{K}_+$	0	0	0
P_+	$2\sqrt{2}iD_+$	0	$\sqrt{2}iP_+$	0	0	0
D_+	$\sqrt{2}i\mathfrak{K}_+$	$-\sqrt{2}iP_+$	0	0	0	0
\mathfrak{K}_-	0	0	0	0	$-2\sqrt{2}iD_-$	$-\sqrt{2}i\mathfrak{K}_-$
P_-	0	0	0	$2\sqrt{2}iD_-$	0	$\sqrt{2}iP_-$
D_-	0	0	0	$\sqrt{2}i\mathfrak{K}_-$	$-\sqrt{2}iP_-$	0

IFD vs. LFD





Equal t

$$p^0$$

\leftrightarrow

$$(p^1, p^2)$$

\leftrightarrow

$$p^3$$

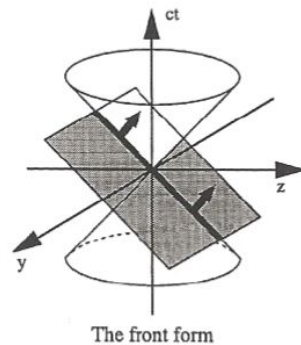
\leftrightarrow

Equal τ

$$p^- = p^0 - p^3$$

$$\vec{p}_\perp$$

$$p^+ = p^0 + p^3$$



Energy-Momentum Dispersion Relations

$$p^0 = \sqrt{\vec{p}^2 + m^2}$$

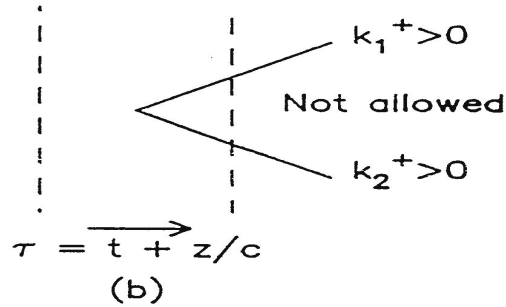
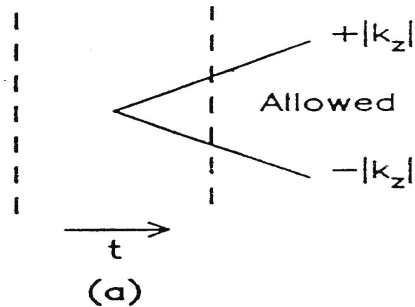
$$p^- = \frac{\vec{p}_\perp^2 + m^2}{p^+}$$

Except zero-modes

$$k_1^+ = k_2^+ = 0$$

IFD

Instant Form Dynamics



LFD

Light-Front Dynamics

Distinguished Vacuum Property

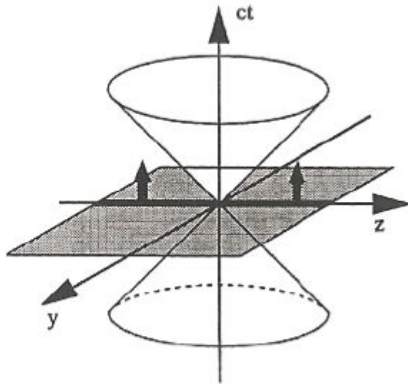
Can IFD and LFD be linked?



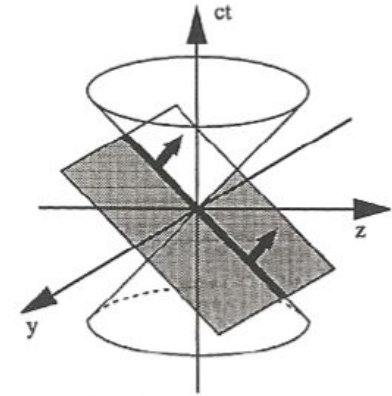
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Yes, they can!



The instant form



The front form

Traditional approach
evolved from NR dynamics

Close contact with
Euclidean space

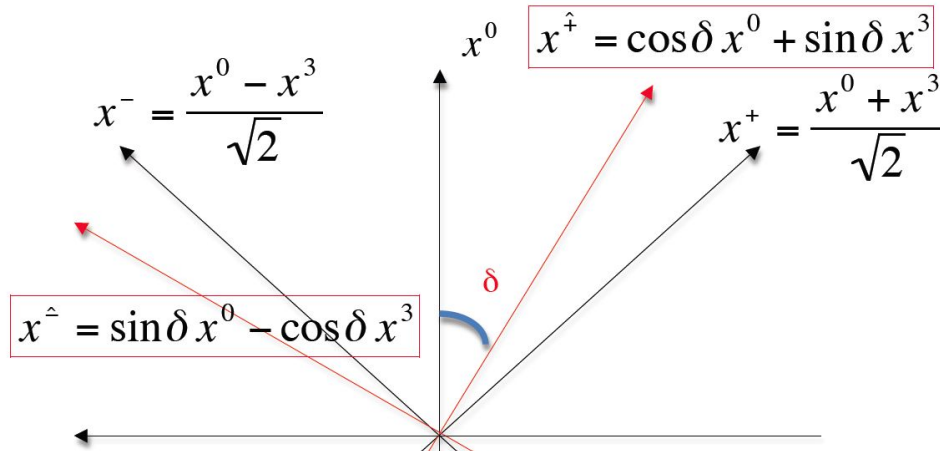
T-dept QFT, LQCD, IMF, etc.

Innovative approach
for relativistic dynamics

Strictly in Minkowski space

DIS, PDFs, DVCS, GPDs, etc.

Interpolation between IFD and LFD



$$(IFD) \quad 0 \leq \delta \leq \frac{\pi}{4} \quad (LFD)$$

$$1 \geq C \equiv \cos(2\delta) \geq 0$$

K. Hornbostel, PRD45, 3781 (1992) – RQFT

C.Ji and S.Rey, PRD53, 5815(1996) – Chiral Anomaly

C.Ji and C. Mitchell, PRD64, 085013 (2001) – Poincare Algebra

C.Ji and A. Suzuki, PRD87, 065015 (2013) – Scattering Amps

C.Ji, Z. Li and A. Suzuki, PRD91, 065020 (2015) – EM Gauges

Z.Li, M. An and C.Ji, PRD92, 105014 (2015) – Spinors

C.Ji, Z.Li, B.Ma and A.Suzuki, PRD98, 036017(2018) – QED

B.Ma and C.Ji, PRD104, 036004(2021) – QCD₁₊₁

C.Ji and H. Ravikumar, PRD113, 096018(2026) – Conformal Symmetry

1 + 1 conformal algebra in the interpolation form

	\mathfrak{K}_+	P_+	D_+	\mathfrak{K}_-	P_-	D_-
\mathfrak{K}_+	0	$-2i[(c + Ss)D_+ + (s - Sc)D_-]$	$-i[(c + Ss)\mathfrak{K}_+ + (s - Sc)\mathfrak{K}_-]$	0	$2iC[sD_+ - cD_-]$	$iC[s\mathfrak{K}_+ - c\mathfrak{K}_-]$
P_+	$2i[(c + Ss)D_+ + (s - Sc)D_-]$	0	$i[(c + Ss)P_+ + (s - Sc)P_-]$	$-2iC[sD_+ - cD_-]$	0	$-iC[sP_+ - cP_-]$
D_+	$i[(c + Ss)\mathfrak{K}_+ + (s - Sc)\mathfrak{K}_-]$	$-i[(c + Ss)P_+ + (s - Sc)P_-]$	0	$-iC[s\mathfrak{K}_+ - c\mathfrak{K}_-]$	$iC[sP_+ - cP_-]$	0
\mathfrak{K}_-	0	$2iC[sD_+ - cD_-]$	$iC[s\mathfrak{K}_+ - c\mathfrak{K}_-]$	0	$-2i[(c - Ss)D_+ + (s + Sc)D_-]$	$-i[(c - Ss)\mathfrak{K}_+ + (s + Sc)\mathfrak{K}_-]$
P_-	$-2iC[sD_+ - cD_-]$	0	$-iC[sP_+ - cP_-]$	$2i[(c - Ss)D_+ + (s + Sc)D_-]$	0	$i[(c - Ss)P_+ + (s + Sc)P_-]$
D_-	$-iC[s\mathfrak{K}_+ - c\mathfrak{K}_-]$	$iC[sP_+ - cP_-]$	0	$i[(c - Ss)\mathfrak{K}_+ + (s + Sc)\mathfrak{K}_-]$	$-i[(c - Ss)P_+ + (s + Sc)P_-]$	0

Interpolation angle	Kinematic	Dynamic
$\delta = 0$	P_3, D	$K_3, P_0, \mathfrak{K}_0, \mathfrak{K}_3$
$0 < \delta < \pi/4$	$P_-, D = (D_+c + D_-s)$	$K_3 = (D_+s - D_-c), P_+, \mathfrak{K}^+, \mathfrak{K}^-$
$\delta = \pi/4$	$P_-, D_+ = \frac{(D+K_3)}{\sqrt{2}}, D_- = \frac{(D-K_3)}{\sqrt{2}}, \mathfrak{K}_-$	P_+, \mathfrak{K}_+

$$g^{\mu\nu} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix} \longrightarrow g^{\hat{\mu}\hat{\nu}} = \begin{bmatrix} \cos 2\delta & 0 & 0 & \sin 2\delta \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ \sin 2\delta & 0 & 0 & -\cos 2\delta \end{bmatrix}$$

$$\int d^3\vec{x} T^{0\mu} = P^\mu = \begin{bmatrix} P^0 \\ P^1 \\ P^2 \\ P^3 \end{bmatrix} \longrightarrow P^{\hat{\mu}} = \begin{bmatrix} P^{\hat{1}} = \cos \delta P^0 + \sin \delta P^3 \\ P^{\hat{2}} = P^1 \\ P^{\hat{3}} = P^2 \\ P^{\hat{4}} = \sin \delta P^0 - \cos \delta P^3 \end{bmatrix} = \int dx^{\hat{4}} d^2\vec{x}_{\perp} T^{\hat{\mu}\hat{\nu}}$$

$$\int d^3\vec{x} (T^{0\mu} x^\nu - T^{0\nu} x^\mu) = J^{\mu\nu} = \begin{bmatrix} 0 & K^1 & K^2 & K^3 \\ -K^1 & 0 & J^3 & -J^2 \\ -K^2 & -J^3 & 0 & J^1 \\ -K^3 & J^2 & -J^1 & 0 \end{bmatrix} \longrightarrow J^{\hat{\mu}\hat{\nu}} = \begin{bmatrix} 0 & \hat{E}^1 & \hat{E}^2 & -K^3 \\ -\hat{E}^1 & 0 & J^3 & -\hat{F}^1 \\ -\hat{E}^2 & -J^3 & 0 & -\hat{F}^2 \\ K^3 & \hat{F}^1 & \hat{F}^2 & 0 \end{bmatrix}$$

$$T^{\mu\nu} = \sum_k \frac{\partial L}{\partial(\partial_\mu \phi_k)} \partial^\nu \phi_k - g^{\mu\nu} L \quad ; \quad \partial_\mu T^{\mu\nu} = 0$$

$$\begin{aligned} \hat{E}^1 &= J^2 \sin \delta + K^1 \cos \delta \\ \hat{E}^2 &= K^2 \cos \delta - J^1 \sin \delta \\ \hat{F}^1 &= K^1 \sin \delta - J^2 \cos \delta \\ \hat{F}^2 &= J^1 \cos \delta + K^2 \sin \delta \end{aligned}$$

Poincaré Algebra

$$[P^{\hat{\mu}}, P^{\hat{\nu}}] = 0 \quad [P^{\hat{\mu}}, J^{\hat{\rho}\hat{\sigma}}] = i(g^{\hat{\mu}\hat{\rho}} P^{\hat{\sigma}} - g^{\hat{\mu}\hat{\sigma}} P^{\hat{\rho}})$$

$$[J^{\hat{\mu}\hat{\nu}}, J^{\hat{\rho}\hat{\sigma}}] = i(g^{\hat{\mu}\hat{\sigma}} J^{\hat{\nu}\hat{\rho}} + g^{\hat{\nu}\hat{\rho}} J^{\hat{\mu}\hat{\sigma}} - g^{\hat{\mu}\hat{\rho}} J^{\hat{\nu}\hat{\sigma}} - g^{\hat{\nu}\hat{\sigma}} J^{\hat{\mu}\hat{\rho}})$$

e.g. $[P^{\hat{\dagger}}, J^{\hat{\dagger}\hat{\wedge}}] = i(g^{\hat{\dagger}\hat{\dagger}} P^{\hat{\wedge}} - g^{\hat{\dagger}\hat{\wedge}} P^{\hat{\dagger}})$

↓

$$[P^{\hat{\dagger}}, -K^3] = i(P^{\hat{\wedge}} \cos 2\delta - P^{\hat{\dagger}} \sin 2\delta)$$

↓ $\delta \rightarrow \pi/4$

$$[K^3, P^+] = -iP^+$$
$$\text{Exp}(-i\omega K^3) |x^+ \rangle \propto |x^+ \rangle$$

One more kinematic generator appears only in the front form.

Maximum number (7) of members in the stability group.

Kinematic Operators (Members of Stability Group)

$$\text{Exp}(-i\omega \hat{\mathcal{K}}^i) |x^{\hat{\dagger}}\rangle \propto |x^{\hat{\dagger}}\rangle$$

$$[\hat{\mathcal{K}}^i, P^{\hat{\dagger}}] = 0$$

$$\hat{\mathcal{K}}^i = \hat{F}^i \cos 2\delta - \hat{E}^i \sin 2\delta$$

$$\begin{aligned} \delta = 0 \\ -J^2 \\ J^1 \end{aligned}$$

$$\hat{\mathcal{K}}^1 = -J^2 \cos \delta - K^1 \sin \delta$$

$$\hat{\mathcal{K}}^2 = J^1 \cos \delta - K^2 \sin \delta$$

$$\delta = \pi/4$$

$$-E^1 = -(J^2 + K^1)/\sqrt{2}$$

$$E^2 = (J^1 - K^2)/\sqrt{2}$$

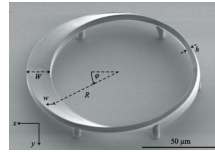
$$(J^3, P^1, P^2, P_z)$$

Orientation Entanglement of Quantum Mechanical Systems

□ The angle should be rotated to get the same initial configuration.

- Spin-0 → Any angle
- Spin-1/2 → 720^0
- Spin-1 → 360^0

$$|0, 0\rangle = \frac{1}{\sqrt{2}}(|\uparrow\downarrow\rangle - |\downarrow\uparrow\rangle)$$



$$|1, 1\rangle = |\uparrow\uparrow\rangle$$

$$|1, 0\rangle = \frac{1}{\sqrt{2}}(|\uparrow\downarrow\rangle + |\downarrow\uparrow\rangle)$$

$$|1, -1\rangle = |\downarrow\downarrow\rangle$$

Rotation by 180^0

$$|0, 0\rangle \longrightarrow |0, 0\rangle$$

$$|1, 0\rangle \longrightarrow -|1, 0\rangle$$

INTERPOLATING HELICITY

$$\delta \rightarrow 0 \quad T_\delta = e^{i\beta_1 \mathcal{K}^1 + i\beta_2 \mathcal{K}^2} e^{-i\beta_3 K^3} \quad \delta \rightarrow \pi/4$$

$$(\mathbb{C} \rightarrow 1) \quad (\mathbb{C} = \cos 2\delta) \quad (\mathbb{C} \rightarrow 0)$$

$$T_I = e^{-i\theta J^2} e^{-i\eta K^3} \quad T_l = e^{-i\beta_1 E^1} e^{-i\beta_3 K^3}$$

$$\mathcal{K}^1 = -K^1 \sin \delta - J^2 \cos \delta,$$

Jacob-Wick Helicity $\mathcal{K}^2 = J^1 \cos \delta - K^2 \sin \delta,$ **Light-Front Helicity**

**D. Dayananda & C.Ji, arXiv:2603.18208v1 [hep-th];
PRD113,116038(2016)**

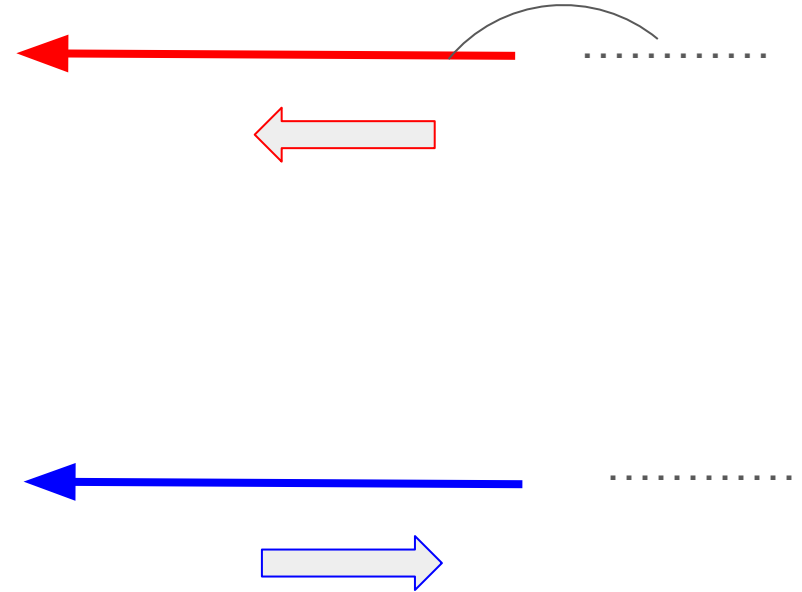
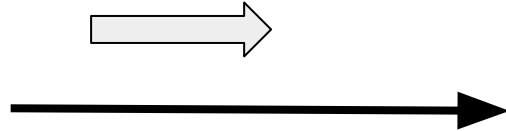
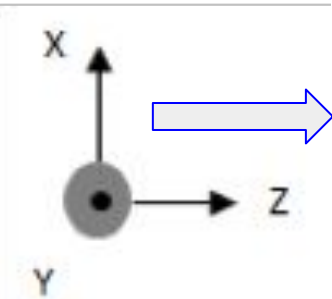
H. Leutwyler and J. Stern, *Ann. Phys. (N.Y.)* **112**, 94 (1978).

Pauli-Lubanski pseudovector $W^\mu = \frac{1}{2} \epsilon^{\mu\nu\alpha\beta} P_\nu M_{\alpha\beta}, \quad \hat{\mathcal{J}}_3 = W^{\hat{+}}/\mathbb{P}.$

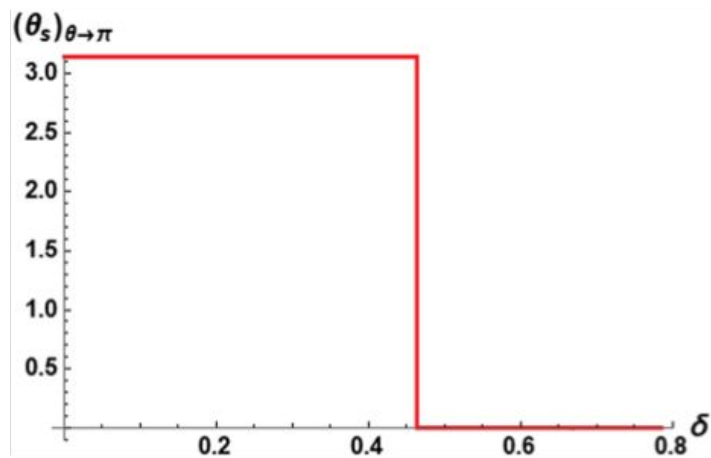
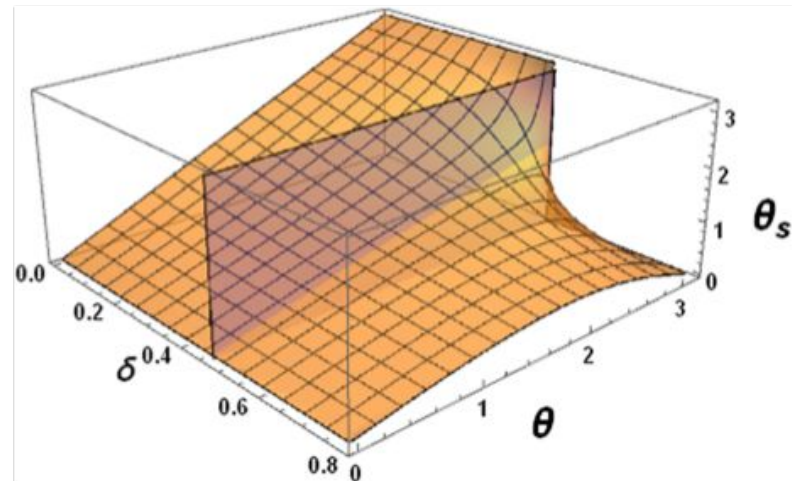
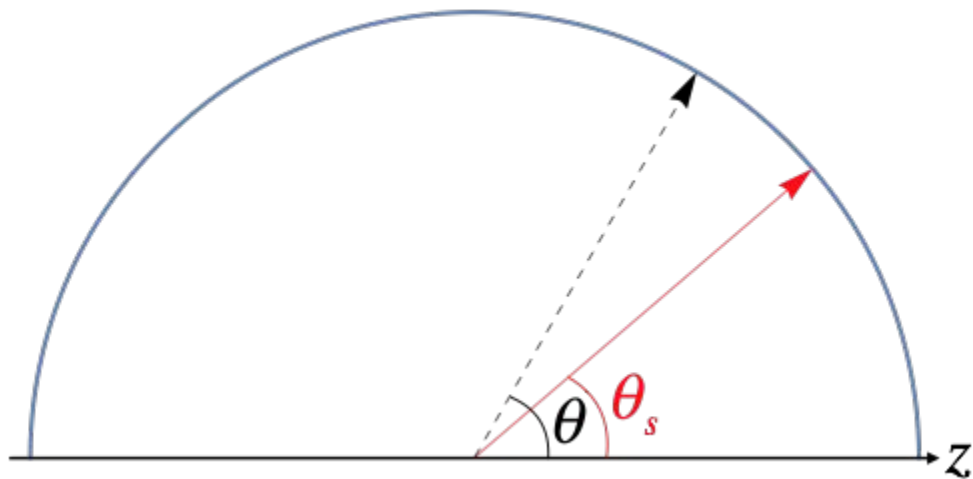
C. Carlson and C.-R. Ji, *Phys. Rev. D* **67** (2003) 116002.

Jacob-Wick Helicity +1

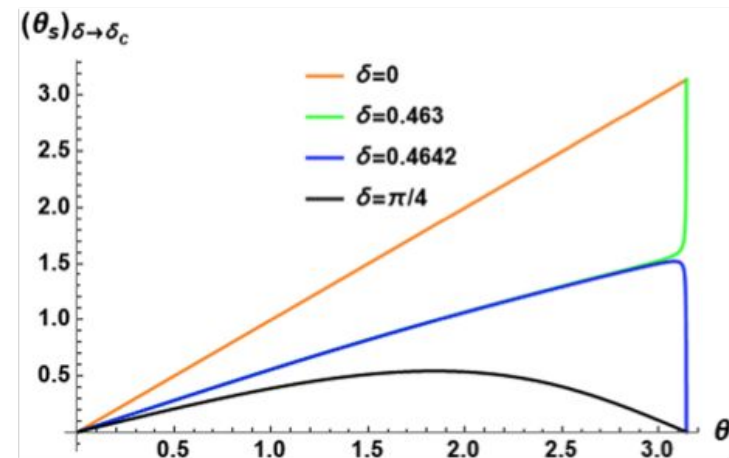
IFD: Transverse Rotation by 180°



**LFD: Longitudinal Boost to flip
Light-Front Helicity +1**



$$\delta_c = \tan^{-1}(P_v/E_0)$$



IFD and LFD are the two different formulations with two different degrees of freedom quantized at the equal time $t = x^0$ vs. at the equal light-front time $\tau \equiv (x^0 + x^3)/\sqrt{2} = x^+$, respectively. They correspond to each other with the interpolating time $x^{\hat{+}} = \cos\delta x^0 + \sin\delta x^3$.

Large N_c QCD in 1+1 dim. ('tHooft Model)

$$\mathcal{L} = -\frac{1}{4} F_{\hat{\mu}\hat{\nu}}^a F^{\hat{\mu}\hat{\nu}a} + \bar{\psi}(i\gamma^{\hat{\mu}} D_{\hat{\mu}} - m)\psi$$

$$D_{\hat{\mu}} = \partial_{\hat{\mu}} - igA_{\hat{\mu}}^a t_a$$

$$F_{\hat{\mu}\hat{\nu}}^a = \partial_{\hat{\mu}} A_{\hat{\nu}}^a - \partial_{\hat{\nu}} A_{\hat{\mu}}^a + gf^{abc} A_{\hat{\mu}}^b A_{\hat{\nu}}^c$$

'tHooft Coupling $\lambda = \frac{g^2 (N_c - 1/N_c)}{4\pi}$ and mass m

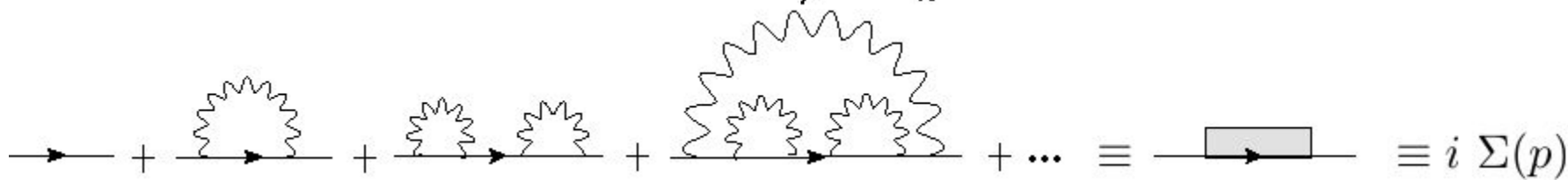
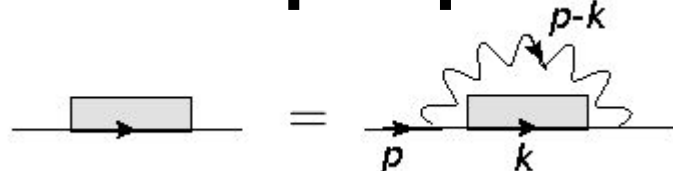
$$g \rightarrow 0, N_c \rightarrow \infty; \lambda \rightarrow \text{finite}$$

Interpolating Axial Gauge

$$A_{\hat{z}}^a = 0$$

$$\mathcal{L} = \frac{1}{2} \left(\partial_{\hat{z}} A_{\hat{z}}^a \right)^2 + \bar{\psi} \left(i\gamma^{\hat{z}} D_{\hat{z}} + i\gamma^{\hat{z}} \partial_{\hat{z}} - m \right) \psi$$

Mass Gap Equation



$$\Sigma(p_{\hat{z}}) = i \frac{\lambda}{2\pi} \int \frac{dk_{\hat{z}} dk_{\hat{z}}}{(p_{\hat{z}} - k_{\hat{z}})^2} \gamma^{\hat{z}} \frac{1}{\not{k} - m - \Sigma(k_{\hat{z}}) + i\epsilon} \gamma^{\hat{z}}$$

Fermion Propagator

Free Propagator

$$S_f(p) = \frac{1}{\not{p} - m + i\epsilon}$$



Interacting Propagator

$$S(p) = \frac{1}{\not{p} - m - \Sigma(p) + i\epsilon}$$
$$= \frac{F(p)}{\not{p} - M(p) + i\epsilon}$$

$$\Sigma(p) = \Sigma_s(p) + \Sigma_v(p)\not{p}$$

$$F(p) = (1 - \Sigma_v(p))^{-1} \quad \text{“Wave function renormalization factor”}$$

$$M(p) = \frac{m + \Sigma_s(p)}{1 - \Sigma_v(p)} \quad \text{“Renormalized fermion mass function”}$$

Energy-Momentum Dispersion Relation

Free particle

Interacting particle

$$E = \sqrt{p_z^2 + m^2}$$

$$\frac{F(p'_\perp)E(p'_\perp)}{\sqrt{C}} = \sqrt{p'^2_\perp + M(p'_\perp)^2} \equiv \tilde{E}(p'_\perp)$$

$$\theta_f = \tan^{-1}(p_z / m)$$

$$\theta(p'_\perp) = \theta_f(p'_\perp) + 2\zeta(p'_\perp)$$

$$\beta = p_z / E$$

$$\begin{pmatrix} b^i(p'_\perp) \\ d^{+i}(p'_\perp) \end{pmatrix} = \begin{pmatrix} \cos\zeta(p'_\perp) & -\sin\zeta(p'_\perp) \\ \sin\zeta(p'_\perp) & \cos\zeta(p'_\perp) \end{pmatrix} \begin{pmatrix} b^i_f(p'_\perp) \\ d^{+i}_f(p'_\perp) \end{pmatrix}$$

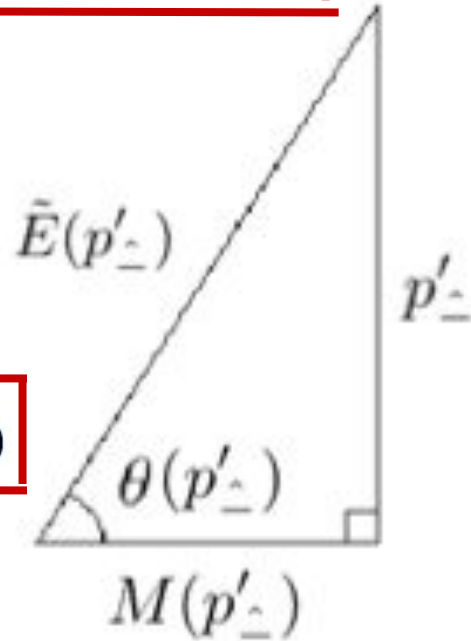
$$= \sin\theta_f$$

$$= \tanh\eta$$

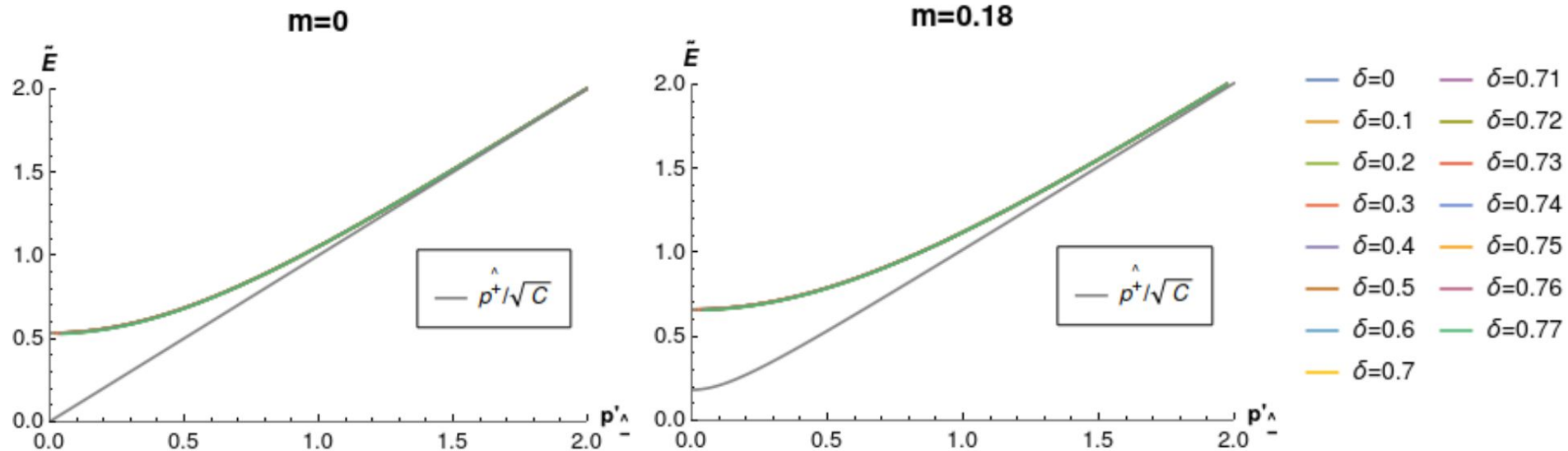
$$b^i_f |0\rangle = 0, d^i_f |0\rangle = 0 \quad \text{vs.} \quad b^i |\Omega\rangle = 0, d^i |\Omega\rangle = 0$$

Interpolation

$$(E, p_z) \Rightarrow (p^\dagger / \sqrt{C}, p_\perp / \sqrt{C} \equiv p'_\perp)$$



Mass Gap Solutions



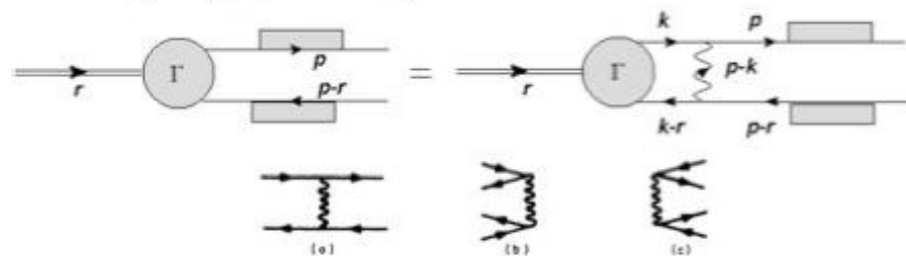
$$\tilde{E}(0) = \frac{F(0)E(0)}{\sqrt{C}} = M(0)$$

m	0	0.045	0.18	0.749	1.00	2.11	4.23
$M(0)$	0.532778	0.563644	0.659112	1.10105	1.31167	2.30969	4.34358
$F(0)$	-0.495173	-0.584175	-0.987673	4.11079	2.17976	1.22134	1.05526

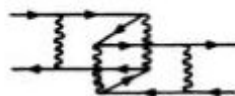
$$m \lesssim 0.56$$

BOUND-STATE EQUATION

$$\Gamma(r, p) = \frac{i\lambda}{2\pi} \int \frac{dk_{\perp} dk_{\parallel}}{(p_{\perp} - k_{\perp})^2} S(p) \gamma^{\dagger} \Gamma(r, k) \gamma^{\dagger} S(p - r)$$



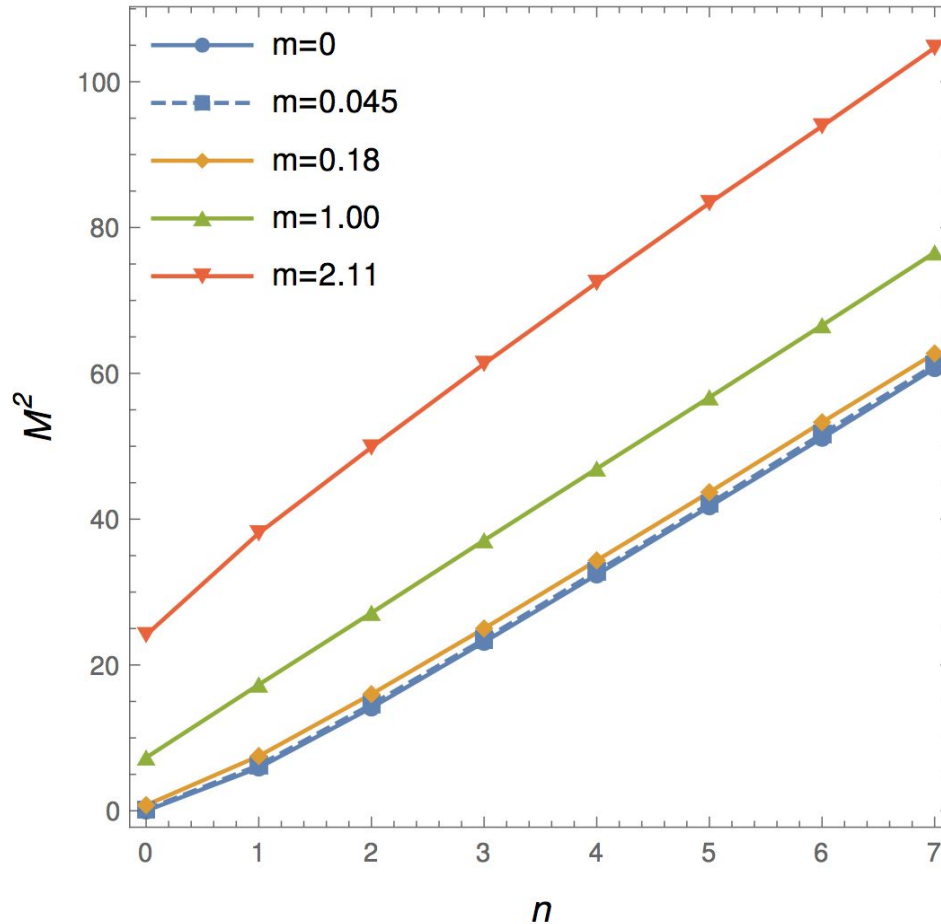
$$\begin{aligned} & \left[-r_{\parallel} + \frac{-S p_{\perp} + E(p_{\perp})}{C} + \frac{S(p_{\perp} - r_{\perp}) + E(p_{\perp} - r_{\perp})}{C} \right] \hat{\phi}_{+}(r_{\perp}, p_{\perp}) \\ &= \lambda \int \frac{dk_{\perp}}{(p_{\perp} - k_{\perp})^2} \left[C(p_{\perp}, k_{\perp}, r_{\perp}) \hat{\phi}_{+}(r_{\perp}, k_{\perp}) - S(p_{\perp}, k_{\perp}, r_{\perp}) \hat{\phi}_{-}(r_{\perp}, k_{\perp}) \right], \\ & \left[r_{\parallel} + \frac{-S(p_{\perp} - r_{\perp}) + E(p_{\perp} - r_{\perp})}{C} + \frac{S p_{\perp} + E(p_{\perp})}{C} \right] \hat{\phi}_{-}(r_{\perp}, p_{\perp}) \\ &= \lambda \int \frac{dk_{\perp}}{(p_{\perp} - k_{\perp})^2} \left[C(p_{\perp}, k_{\perp}, r_{\perp}) \hat{\phi}_{-}(r_{\perp}, k_{\perp}) - S(p_{\perp}, k_{\perp}, r_{\perp}) \hat{\phi}_{+}(r_{\perp}, k_{\perp}) \right]. \end{aligned}$$



LFD

$$\left[\mathcal{M}^2 - \frac{m^2 - 2\lambda}{x} - \frac{m^2 - 2\lambda}{1-x} \right] \phi(x) = -2\lambda \int_0^1 \frac{dy}{(x-y)^2} \phi(y)$$

Meson Spectroscopy

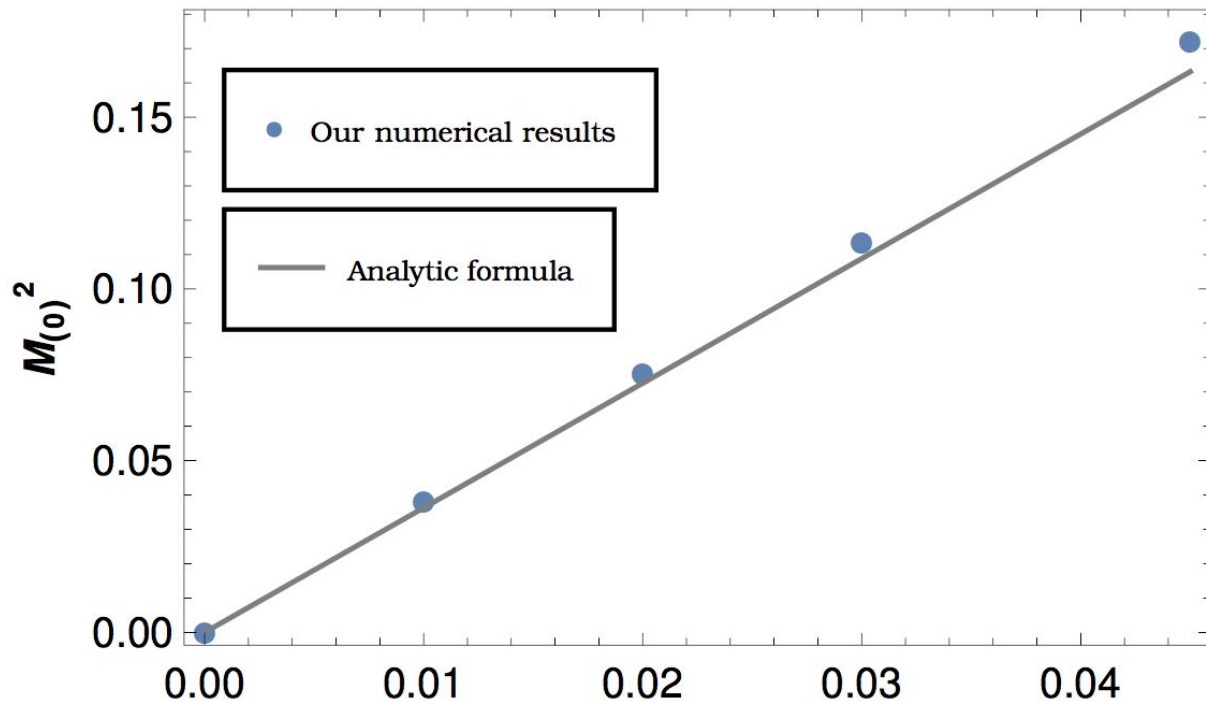


- G. 'tHooft, NPB75, 461(74) - LFD

- M.Li, et al., JPG13, 915(87) - IFD (rest frame)

- Y. Jia, et al., JHEP11, 151('17) - IFD (moving frame)

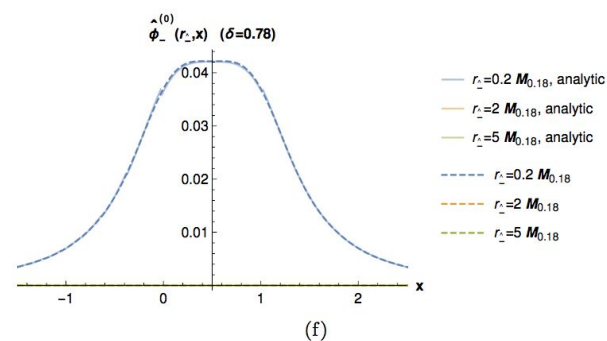
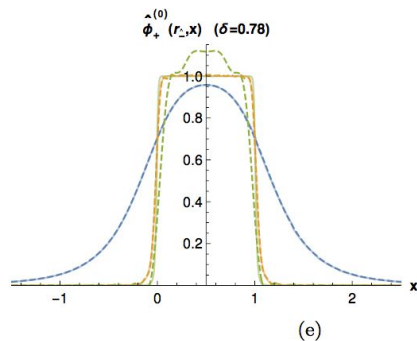
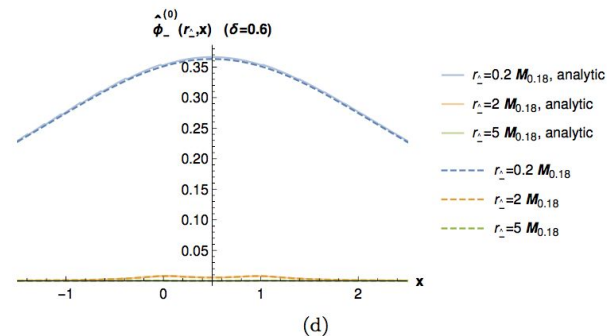
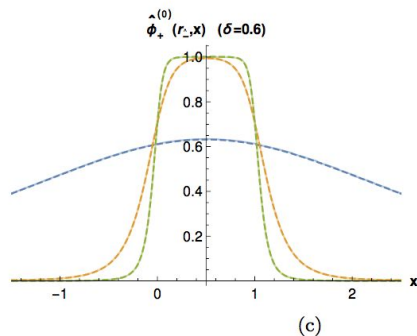
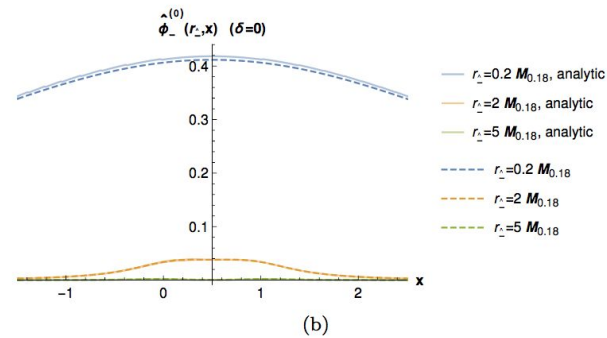
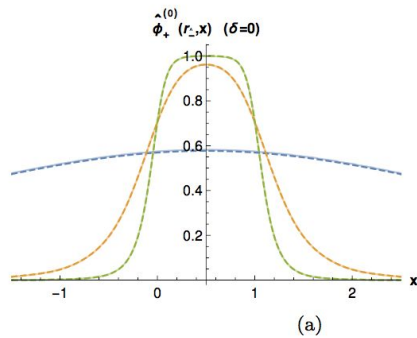
Gell-Mann - Oaks - Renner Relation



$$\mathcal{M}_{\pi}^2 = -\frac{4m \langle \bar{\psi}\psi \rangle}{f_{\pi}^2} = \sqrt{\frac{8\pi^2 m^2 \lambda}{3}} \quad m \quad f_{\pi} = \sqrt{N_c/\pi}$$

Meson Ground-state Wave-function for $m=0$ case

$$\hat{\phi}_{\pm}^{(0)}(r_{\pm}, p_{\pm}) = \frac{1}{2} \left(\cos \frac{\theta(r_{\pm} - p_{\pm}) - \theta(p_{\pm})}{2} \pm \sin \frac{\theta(r_{\pm} - p_{\pm}) + \theta(p_{\pm})}{2} \right)$$



Parton Distribution Functions (PDFs)

$$q_n(x) = \int_{-\infty}^{+\infty} \frac{d\xi^-}{4\pi} e^{-ixP^+\xi^-} \\ \times \langle P_n^-, P^+ | \bar{\psi}(\xi^-) \gamma^+ \mathcal{W}[\xi^-, 0] \psi(0) | P_n^-, P^+ \rangle_C,$$

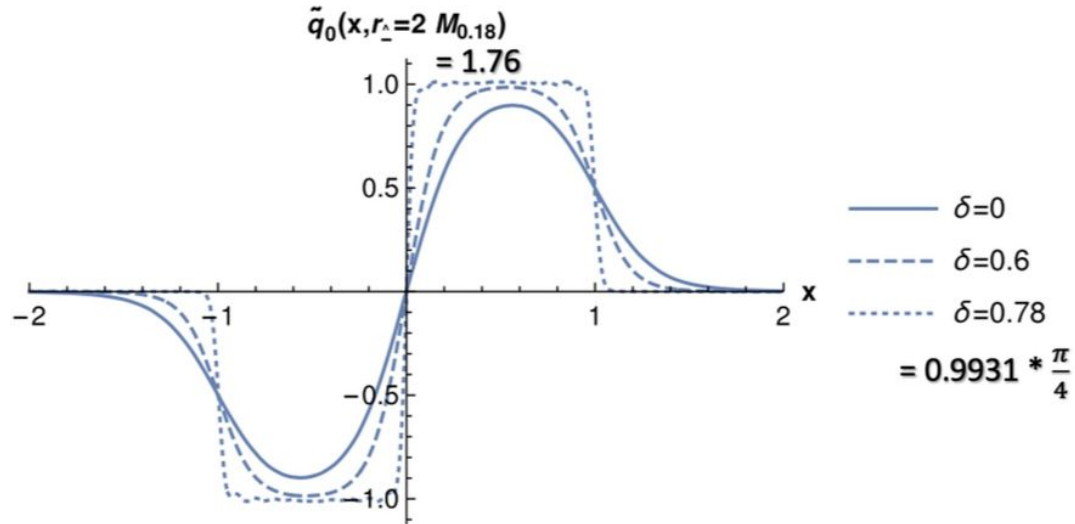
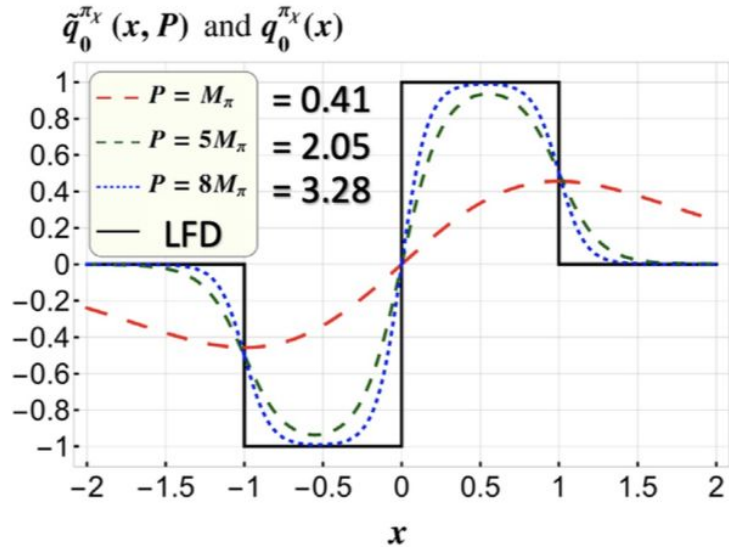
$$\mathcal{W}[\xi^-, 0] = \mathcal{P} \left[\exp \left(-ig_s \int_0^{\xi^-} d\eta^- A^+(\eta^-) \right) \right] \mathbf{A^+=0 Gauge in LFD}$$

Quasi-PDFs

$$\tilde{q}_{(n)}(\hat{r}_\perp, x) = \int_{-\infty}^{+\infty} \frac{dx^\hat{-}}{4\pi} e^{ix^\hat{-} r_\perp} \\ \times \langle r_{(n)}^\hat{+}, r_\perp | \bar{\psi}(x^\hat{-}) \gamma_\perp \mathcal{W}[x^\hat{-}, 0] \psi(0) | r_{(n)}^\hat{+}, r_\perp \rangle_C,$$

$$\mathcal{W}[x^\hat{-}, 0] = \mathcal{P} \left[\exp \left(-ig \int_0^{x^\hat{-}} dx'^\hat{-} A_\perp(x'^\hat{-}) \right) \right] \mathbf{Interpolating dynamics}$$

Y. Jia, et al., PRD98, 054011('18)
- IFD (quasi-PDFs)



B.Ma&C.Ji, PRD104, 036004('21)
- Interpolating Dynamics

Conclusions and Outlook

- **Conformal symmetry nature of the spacetime physics provides distinctively different features between the IFD and the LFD.**
- **Universal orientation entanglement nature distinguishes the relativistic helicities between the IFD and the LFD, i.e. Jacob-Wick helicity \neq Light-front helicity.**
- **Interpolation between IFD and LFD identifies the critical point that bifurcates the two branches of helicities.**
- **Link between QCD and LFQM may be feasible as exemplified by the mass gap solution in the 't Hooft model interpolation between IFD and LFD.**

Conclusions and Outlook

- **BT construction provides the self-consistency of LFQM which assures the component and frame independence of the physical observables.**

Ref: H.M.Choi's talk today's afternoon

- **Universal entanglement nature in color dynamics can be investigated in the deuteron structure studies.**

Ref: S.Kaur's talk Friday afternoon